



Secure Autonomous Systems

CSCI 6907/3907 86

Spring 2024

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<https://bit.ly/secureauto-spring24>

Autonomy



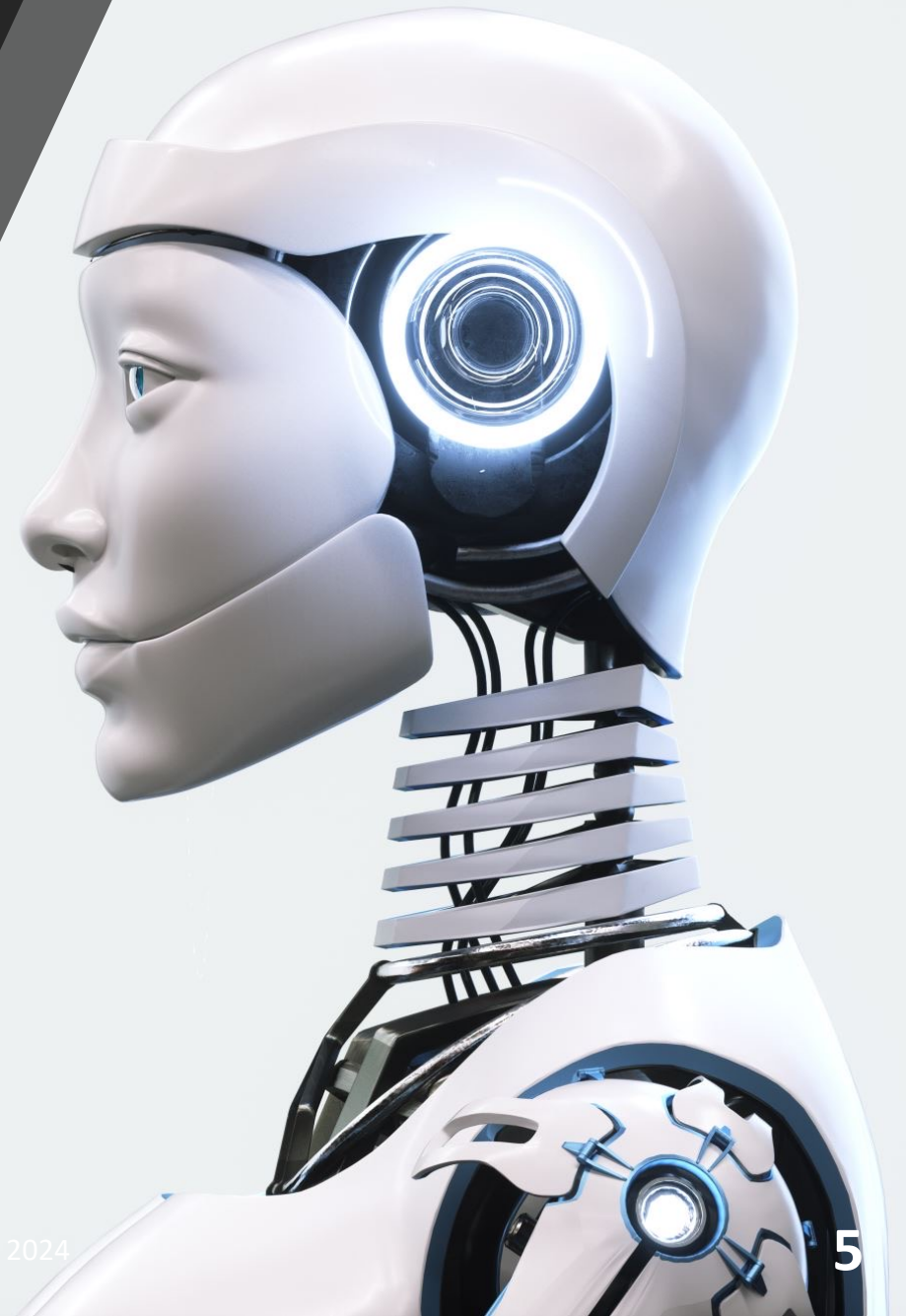
What makes something “autonomous”?

Aspects of Autonomy?

- Perception
- Compute
- Actuation
- Planning
- Sensing
- Motion

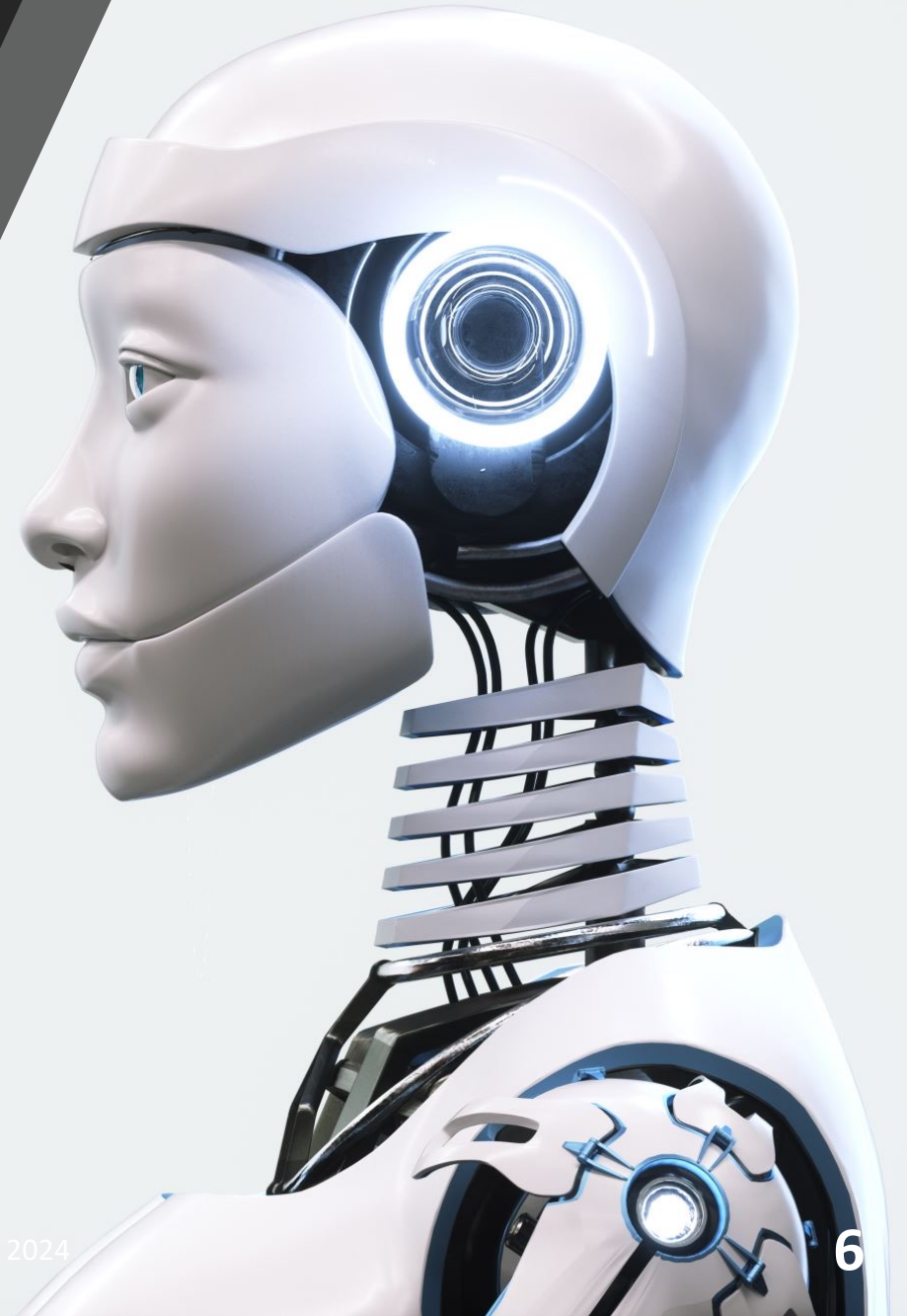
Autonomy | A Definition

Autonomy



Autonomy | A Definition

Autonomy is the **ability to perform given tasks** based on the **system's perception** **without** human intervention



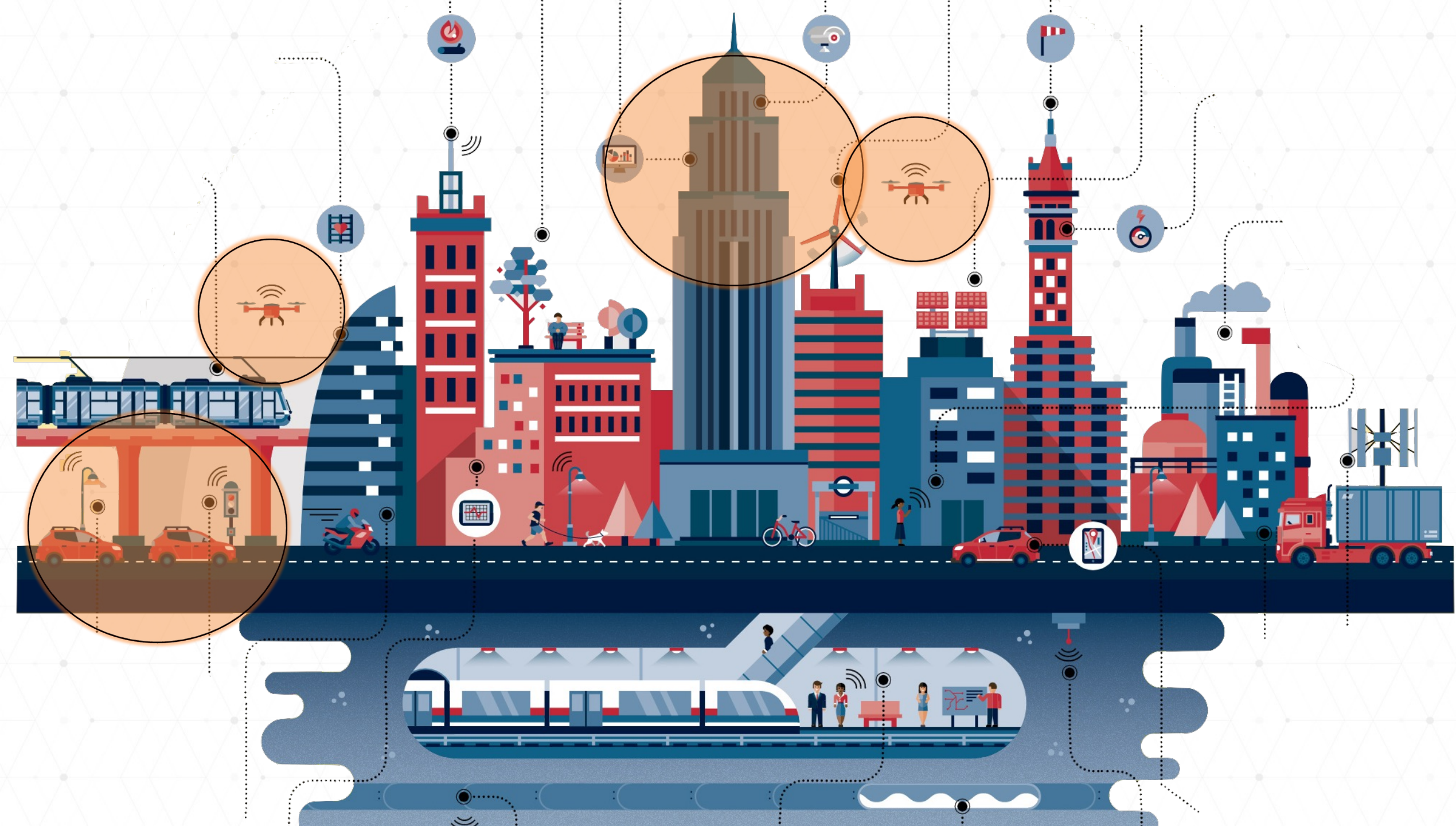
Basic Definitions/ Concepts

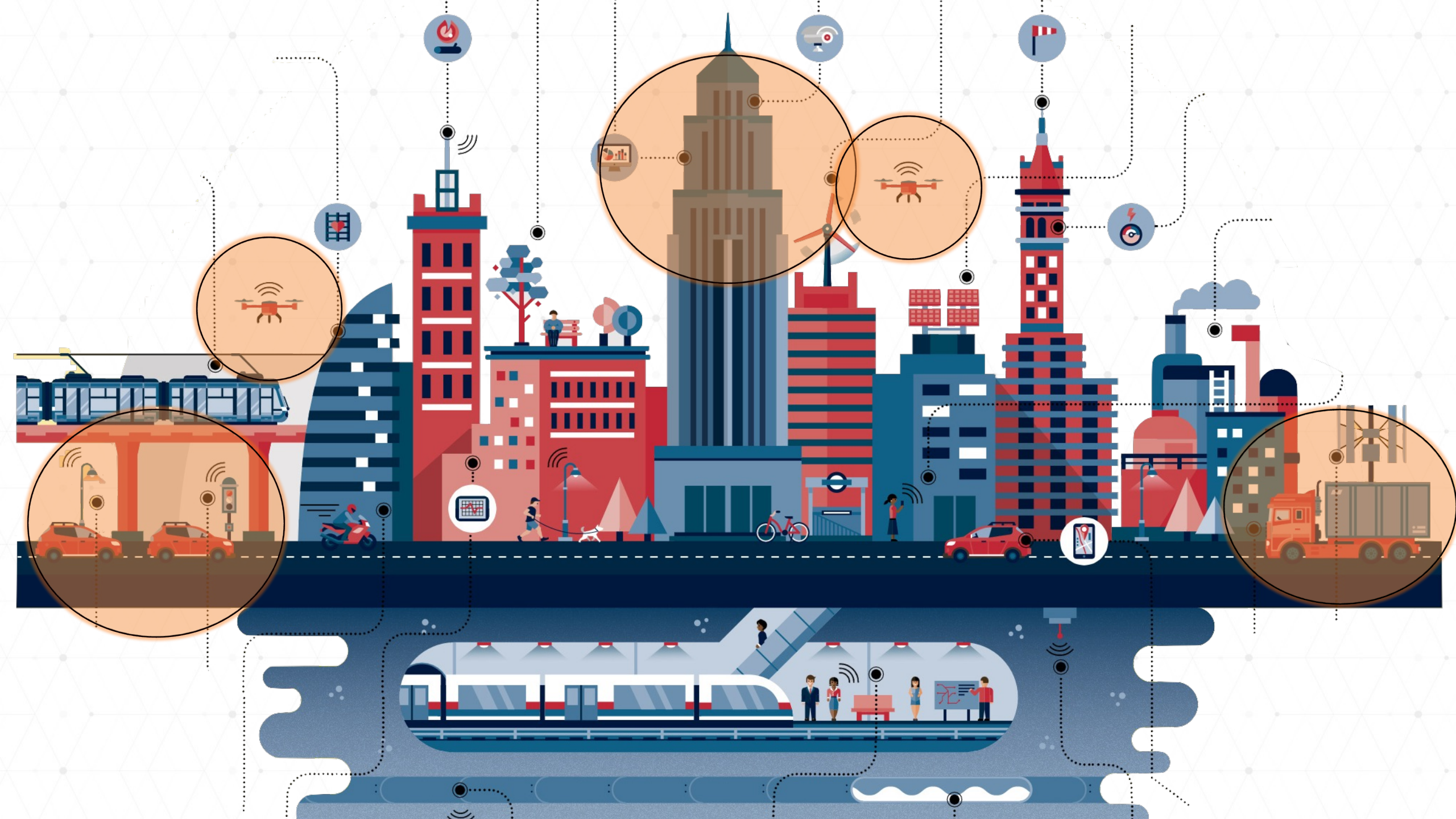
- Cyber-Physical Systems
- Real-Time Systems
- Security/Safety/Resiliency







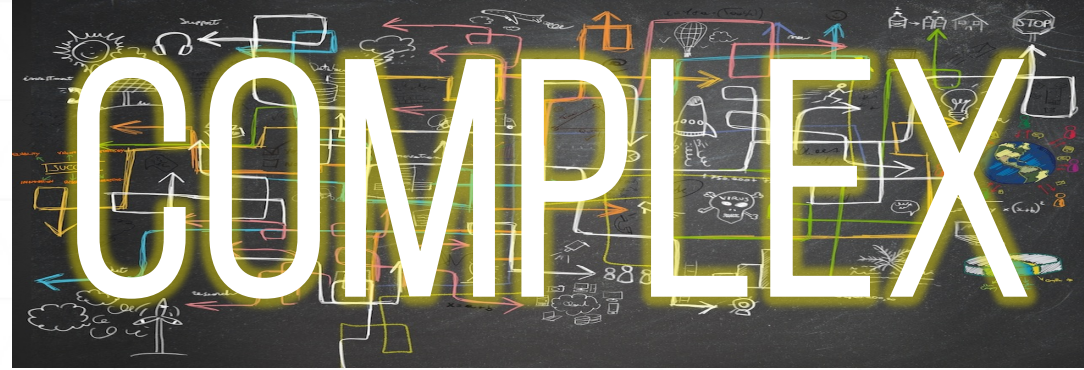




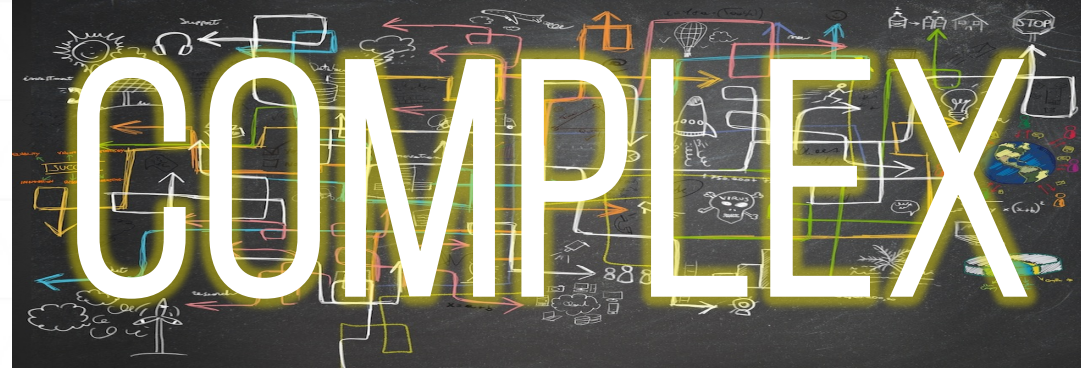


LARGE

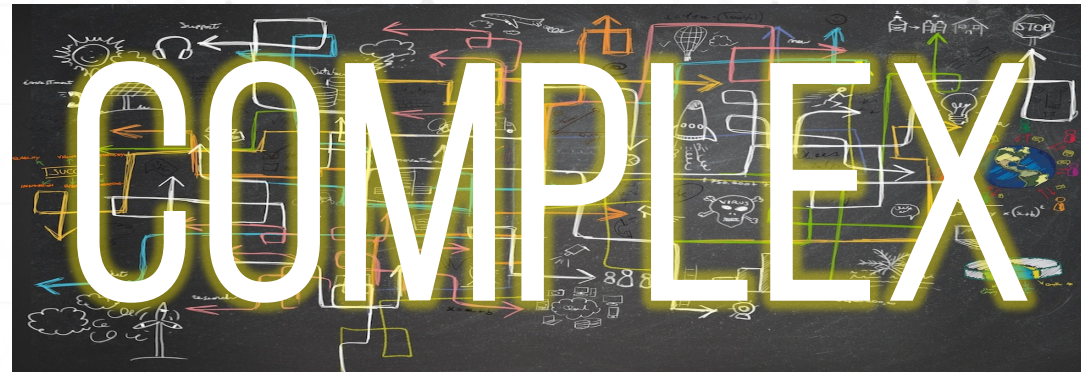
LARGE



LARGE



LARGE



SYSTEMS

LARGE

COMPLEX

MODELING, ANALYSIS, SECURITY ARE **HARD PROBLEMS**

INTERCONNECTED

SYSTEMS

CYBER-PHYSICAL SYSTEMS

CYBER-PHYSICAL SYSTEMS

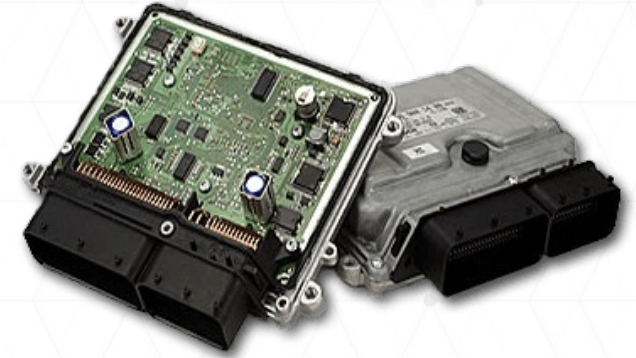
CYBER

```
005 P40A/P TC TEMPR60 # HELLO THERE...
006 P40A/P TC BANKCALL # FOR GENERALIZED RETURN TO OTHER BANKS.
007 CADR G+N,AUTO# AND AUTO STABILIZATION MODES
008 CCS A # +0 INDICATES IN PGNCs, IN AUTO
009 TCF TURNITON # + INDICATES NOT IN PGNCs AND/OR AUTO
010 CAF APSFLBIT # ARE WE ON THE DESCENT STAGE?
011 HASK FLOWRD10
012 CCS A
013 TCF GOBACK # RETURN
014 CAF BITS # YES, CHECK FOR AUTO-THROTTLE MODE
015 EXTEND
016 RAND CHAN30
017 EXTEND
018 BZF GOBACK # IN AUTO-THROTTLE MODE -- RETURN
019 CAF P40A/PPD # DISPLAYS V50N25 R1=203 PLEASE PERFORM
020 TC BANKCALL # CHECKLIST 203 TURN ON PGNCs ETC..
021 CADR GOPERF1
022 TCF GOTOP00H # V34E TERMINATE
023 TCF P40A/P # RECYCLE
024 GOBACK CA TEMPR60
TC BANKCALL # GOODBYE. (P40A/PPD) 000H
```

software, control algorithms, code



networking, communication



ECUs, microcontrollers, PLCs

CYBER-PHYSICAL SYSTEMS

CYBER

```
005 P40A/P TC TEMPR60 # FOR GENERALIZED RETURN TO OTHER BANKS
006 TC BANKCALL # SUBROUTINE TO CHECK PGNC'S CONTROL
007 CADR G+N,AUTO# AND AUTO STABILIZATION MODES
008 CCS A # +0 INDICATES IN PGNC'S, IN AUTO
009 TCF TURNITON # + INDICATES NOT IN PGNC'S AND/OR AUTO
010 CAF APSFLBIT # ARE WE ON THE DESCENT STAGE?
011 HASK FLOWRD10
012 CCS A
013 TCF GOBACK # RETURN
014 CAF BITS # YES, CHECK FOR AUTO-THROTTLE MODE
015 EXTEND
016 RAND CHAN30
017 EXTEND
018 BZF GOBACK # IN AUTO-THROTTLE MODE -- RETURN
019 CAF P40A/PPD # DISPLAYS V50N25 R1=203 PLEASE PERFORM
020 TC BANKCALL # CHECKLIST 203 TURN ON PGNC'S ETC.
021 CADR GOPERF1
022 TCF GOTOPO0H # V34E TERMINATE
023 TCF P40A/P # RECYCLE
024 GOBACK CA TEMPR60
TC BANKCALL # CONTINUE FROM ABOVE CODE
```

software, control algorithms, code



networking, communication



ECUs, microcontrollers, PLCs

PHYSICAL



sensors



actuators, motors



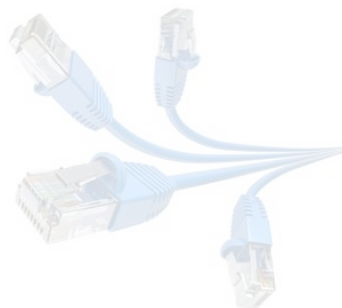
"plants"

CYBER-PHYSICAL SYSTEMS

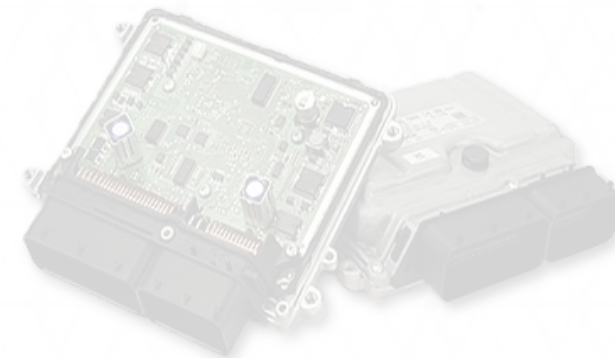
CYBER

```
10 P4BA/P TS TEMPROG # FOR GENERALIZED RETURN TO OTHER BANKS
11 TC BANKCALL # SUBROUTINE TO CHECK PONGS CONTROL
12 CADR G4R,AUTOH AND AUTO STABILIZATION MODES
13 CCS A # *B INDICATES IN PONGS, IN AUTO
14 TCF TURNITON # * INDICATES NOT IN PONGS AND/OR AUTO
15 CAF APSFLRBT # ARE WE ON THE DESCENT STAGE?
16 HASK FLOWRDSB
17 CCS A
18 TCF GDBACK # RETURN
19 CAF BITS # YES, CHECK FOR AUTO-THROTTLE MODE
20 EXTEND
21 RAND CHAN30
22 EXTEND
23 RZF GDBACK # IN AUTO-THROTTLE MODE -- RETURN
24 TURNITON CAF P4BA/PMD # DISPLAYS VSRN25 R1+203 PLEASE PERFORM
25 TC BANKCALL # CHECKLIST 203 TURN ON PONGS ETC.
26 CADR GDBPERF1
27 TCF GDTOPRHH # V34E TERMINATE
28 TCF P4BA/P # RECYCLE
29 GDBACK CA TEMPROG
```

software, control algorithms, code



networking, communication



ECUs, microcontrollers, PLCs

PHYSICAL



sensors



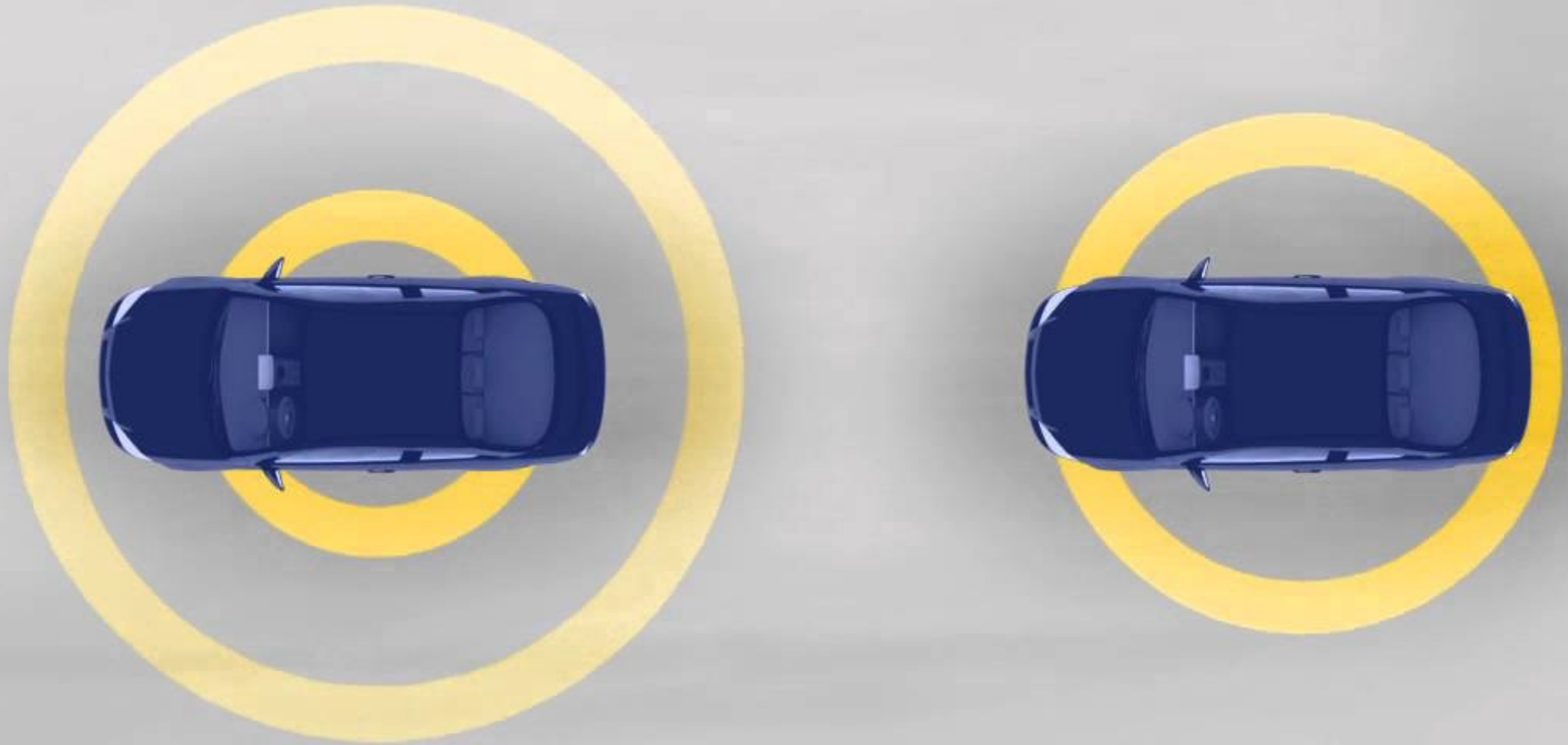
actuators, motors



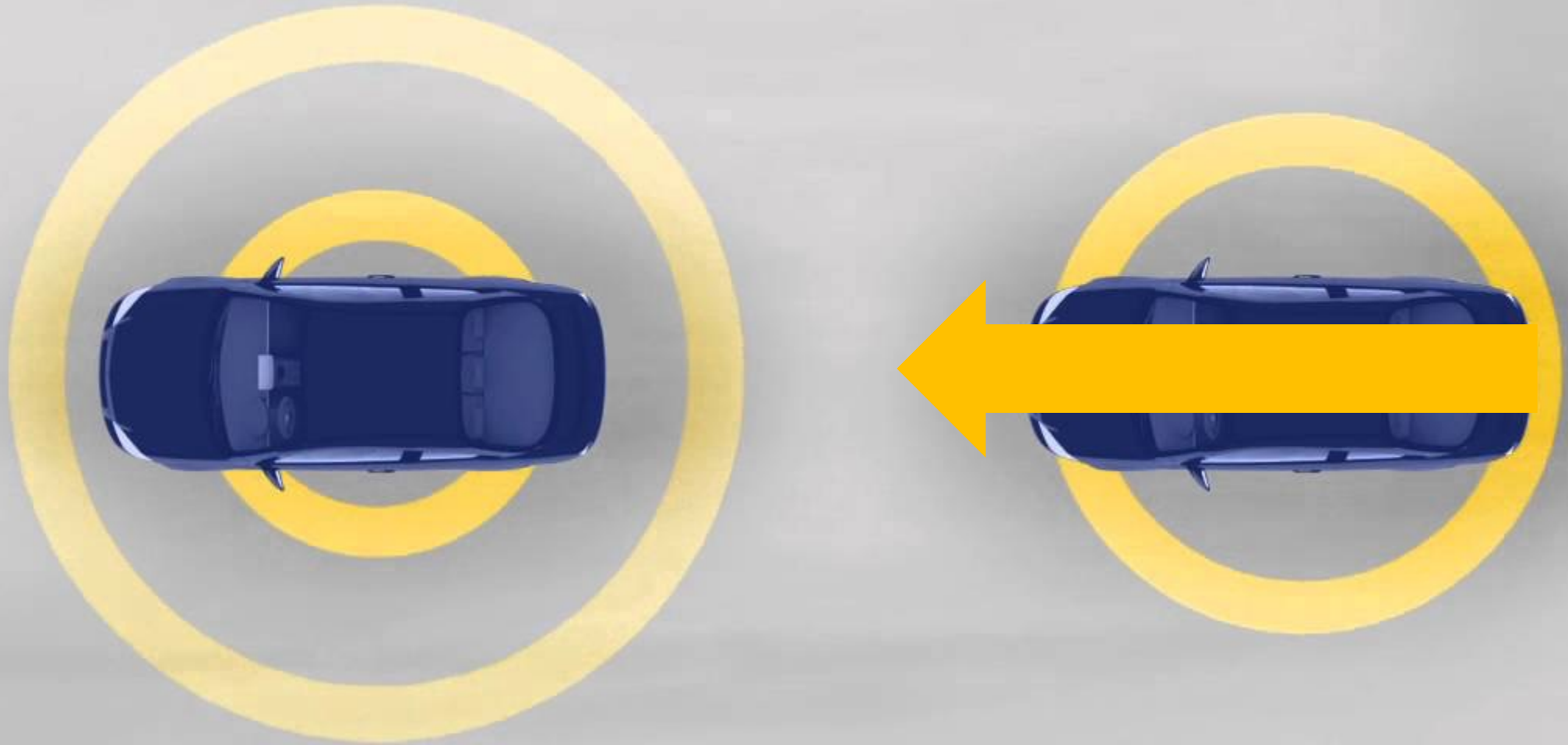
"plants"

SENSING AND ACTUATION IS EVERYWHERE

SENSING/ACTUATION IN THE REAL WORLD

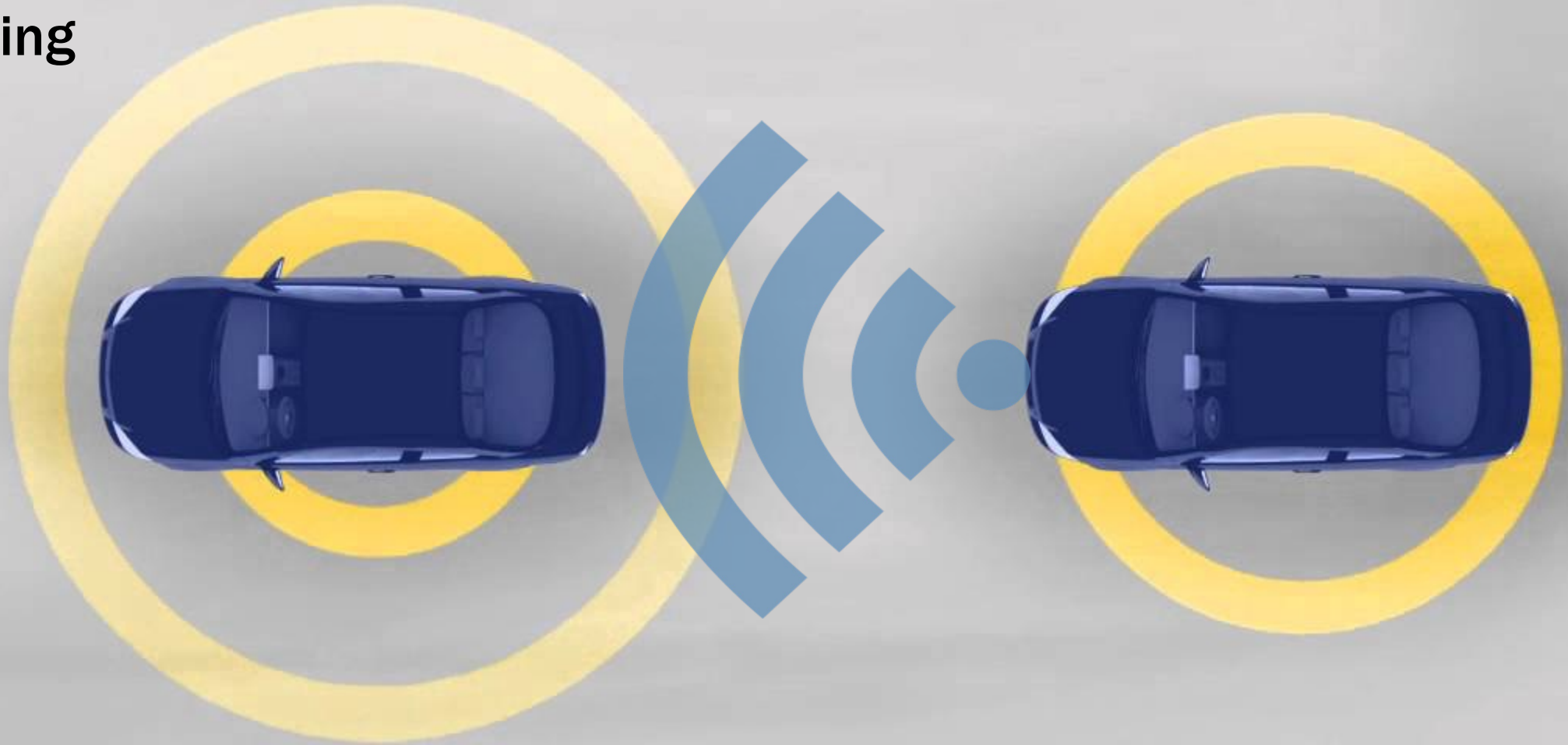


SENSING/ACTUATION IN THE REAL WORLD



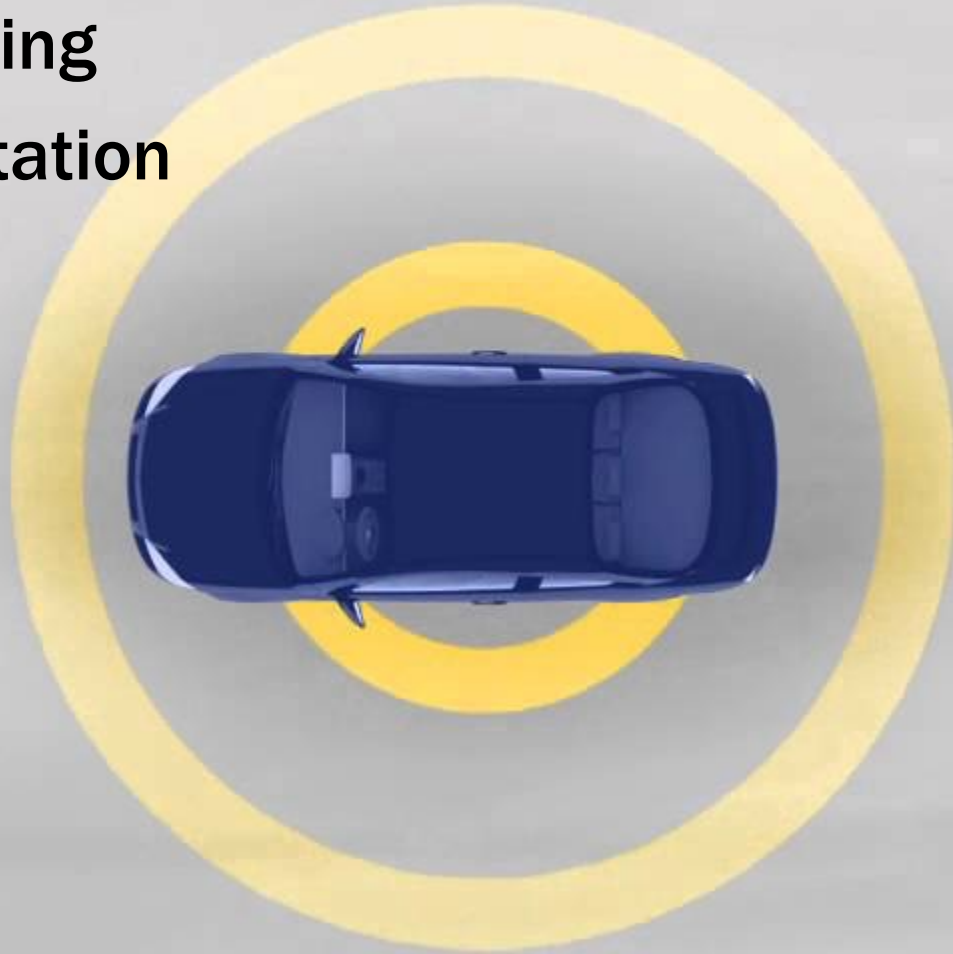
SENSING/ACTUATION IN THE REAL WORLD

- **Periodic Sensing**



SENSING/ACTUATION IN THE REAL WORLD

- Periodic Sensing
- Quick computation



SENSING/ACTUATION IN THE REAL WORLD

- Periodic sensing
- Quick computation
- In time actuation



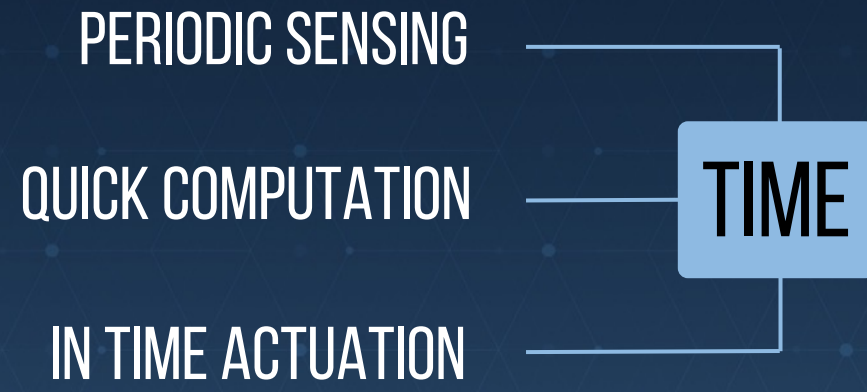
BRAKING



PERIODIC SENSING

QUICK COMPUTATION

IN TIME ACTUATION



REAL-TIME SYSTEMS

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“A system that requires both, **logical** as well as **temporal** correctness.”

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- **Temporal correctness defined as a constraint: deadline**

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- **Deadlines determine usefulness of results**
 - **Deadline passes → usefulness drops**

REAL-TIME SYSTEMS

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 - **Deadline passes → usefulness drops**
- **Use well-defined scheduling algorithms [e.g. RM, EDF]**

REAL-TIME SYSTEMS

“A system that requires both, **logical** as well as **temporal** correctness.”

- **Temporal correctness defined as a constraint: deadline**
- **Deadlines determine usefulness of results**
 - **Deadline passes → usefulness drops**
- **Use well-defined scheduling algorithms [e.g. RM, EDF]**

ONE OF THE FOUNDATIONAL AREAS FOR CYBER-PHYSICAL SYSTEMS

REAL-TIME SYSTEMS

Consider an airbag deployment system



REAL-TIME SYSTEMS

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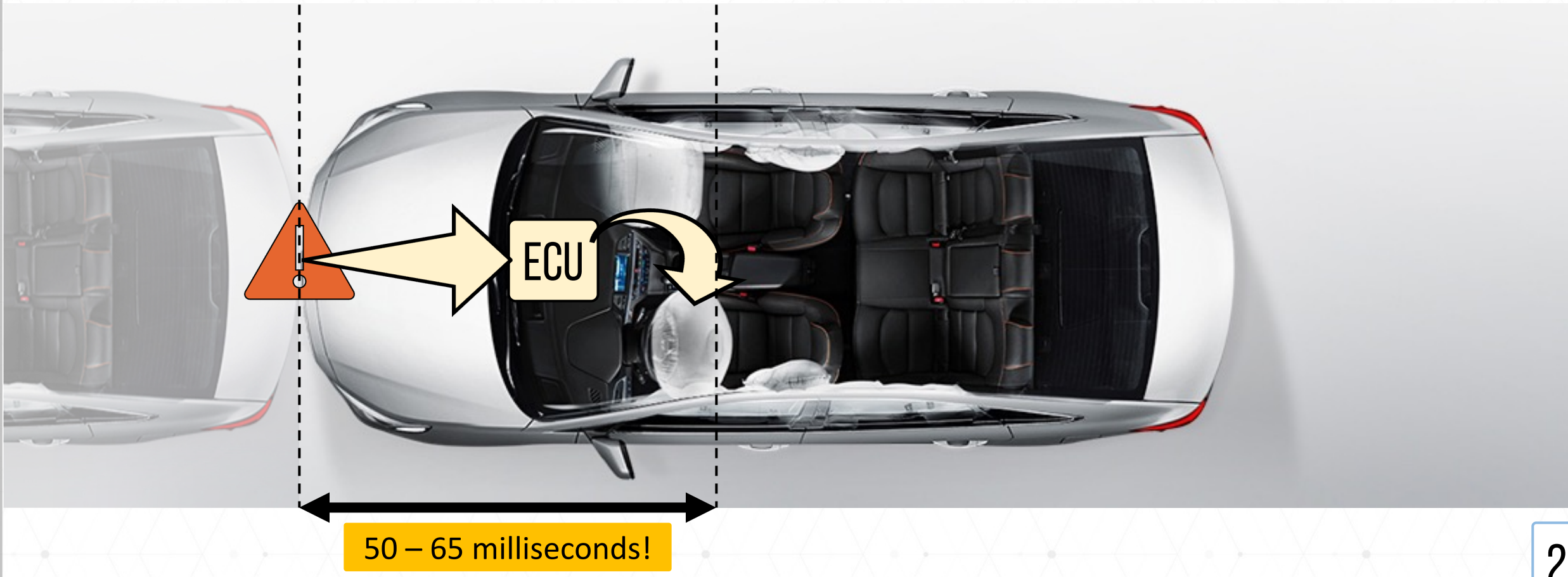
REAL-TIME SYSTEMS

Consider an airbag deployment system



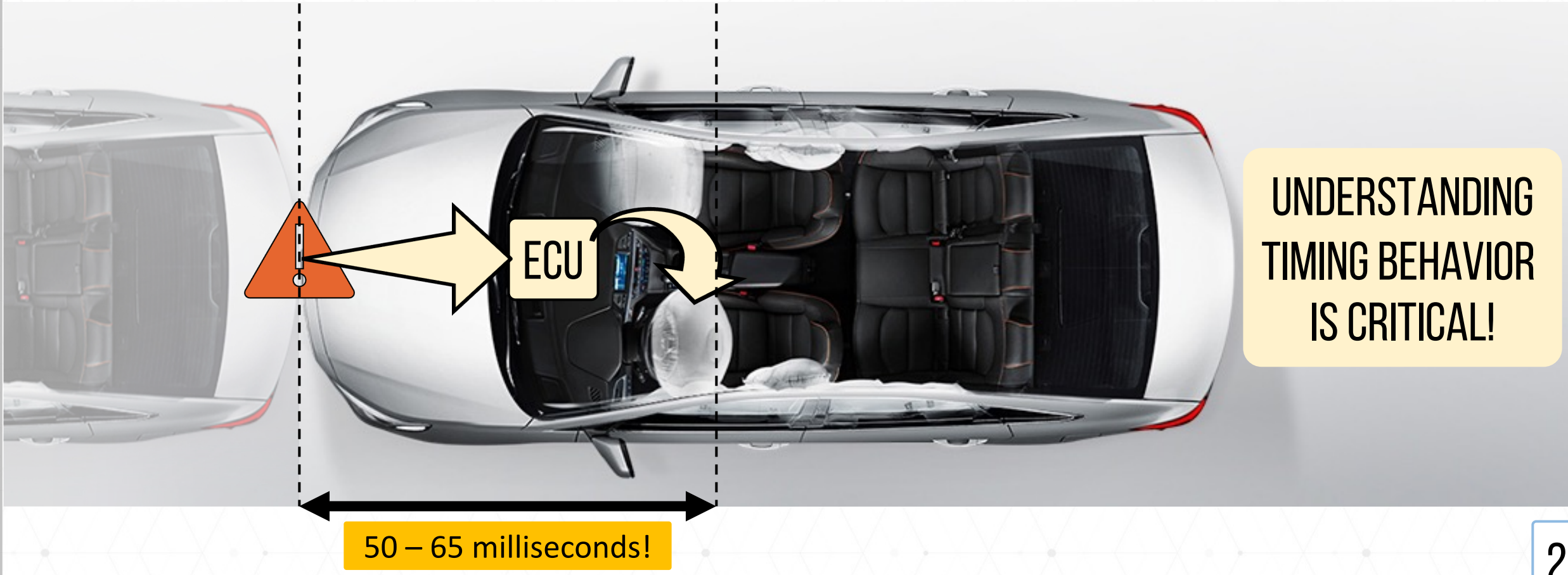
REAL-TIME SYSTEMS

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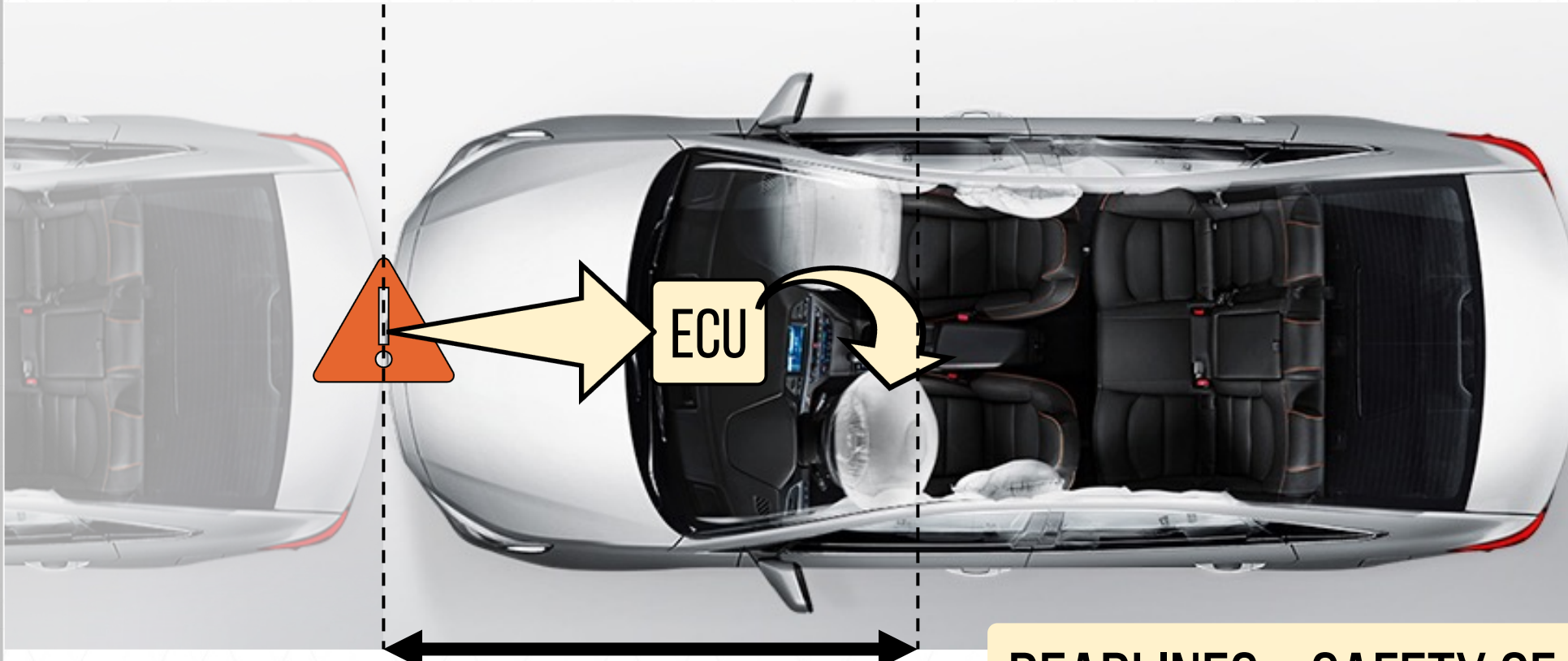
REAL-TIME SYSTEMS

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REAL-TIME SYSTEMS

Consider an airbag deployment system



UNDERSTANDING
TIMING BEHAVIOR
IS CRITICAL!

DEADLINES = SAFETY OF PHYSICAL SYSTEM

50 – 65 milliseconds!

REAL-TIME SYSTEMS

Consider an airbag deployment system

WHY NOT RUN CODE REALLY FAST?

UNDERSTANDING
TIMING BEHAVIOR
IS CRITICAL!

50 – 65 milliseconds!

CPS Challenges



Limited Resources

- Computational power, energy, cost



Timing Requirement

- Safety, reliability, deadlines

CPS Challenges



Limited Resources

- Computational power, energy, cost



Timing Requirement

- Safety, reliability, deadlines



Security/System Upgradability

- Schedulability, Verifiability

CPS

SECURITY

Physically isolated

Specialized protocols & hardware

Not connected to the internet

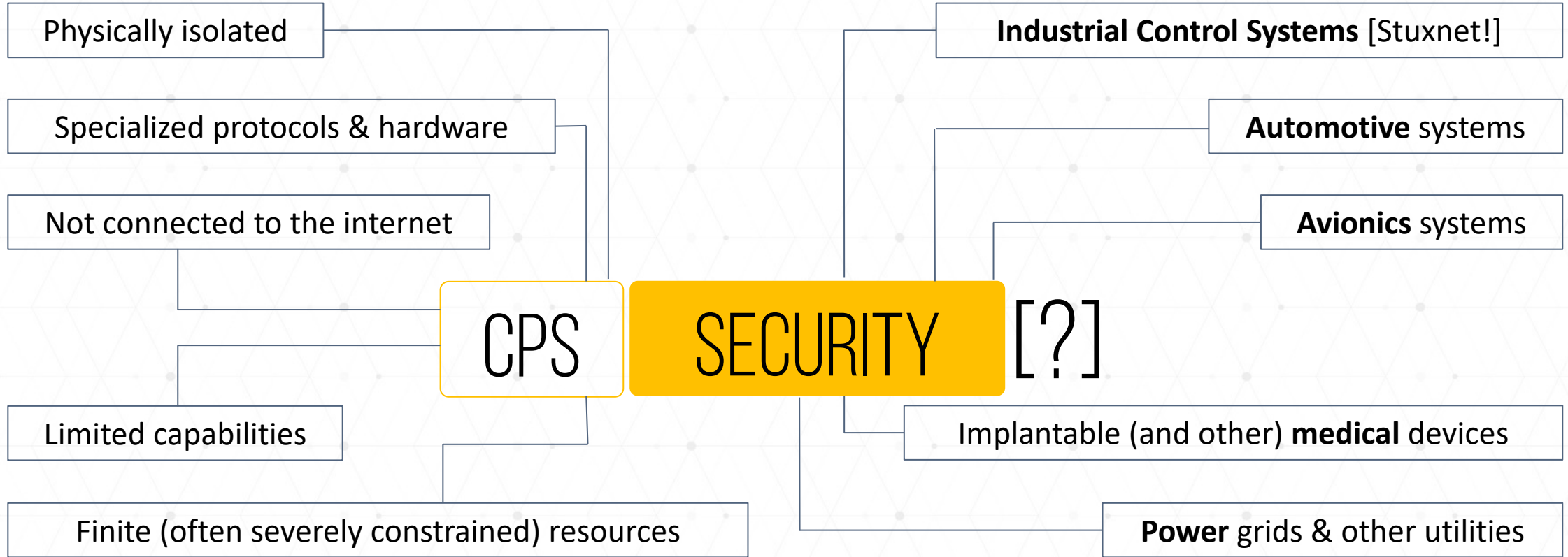
CPS

SECURITY

[?]

Limited capabilities

Finite (often severely constrained) resources



Autonomous Cars

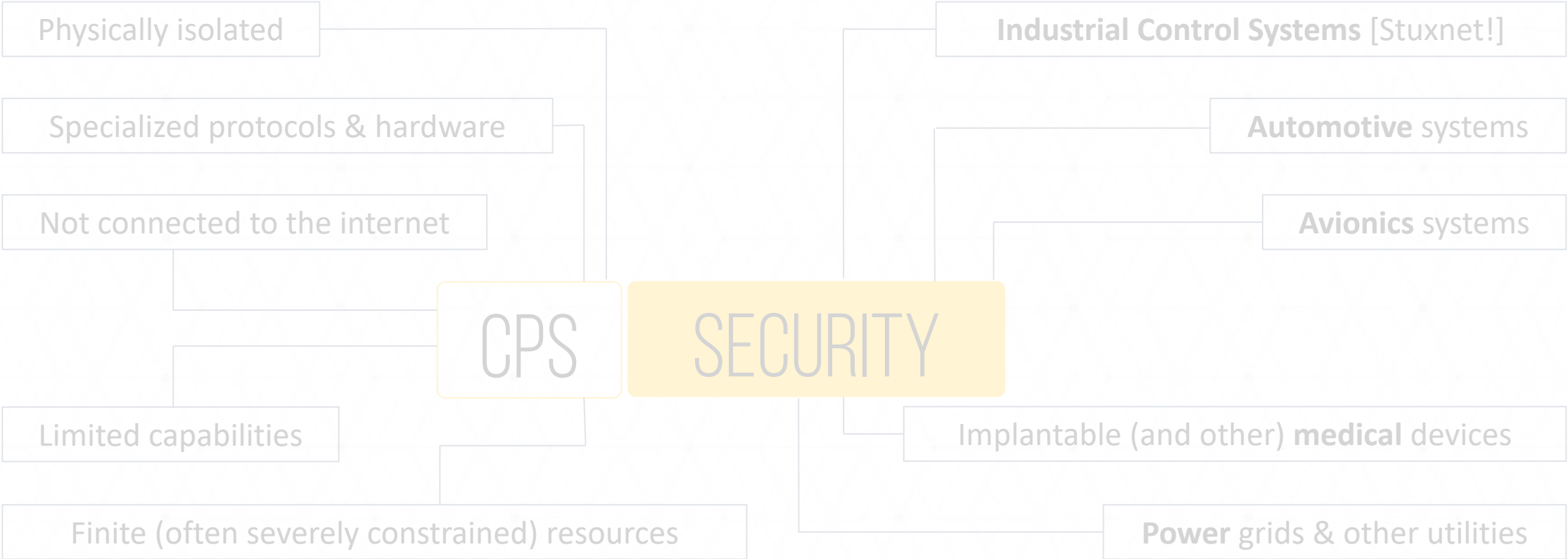
UAVs

Medical/surgical robots

IoT

Delivery robots

Smart Manufacturing Systems



Autonomous Cars

UAVs

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IoT

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Smart Manufacturing Systems

Physically isolated

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CPS

SECURITY

RESILIENCY

Industrial Control Systems [Stuxnet!]

Automotive systems

Avionics systems

Implantable (and other) medical devices

Power grids & other utilities

RESILIENCY?

RESILIENCY?

SOFTWARE ERRORS CAN RESULT IN PHYSICAL FAILURES

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SOFTWARE ERRORS CAN RESULT IN PHYSICAL FAILURES



SECURITY AND RESILIENCY

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ATTACKER INTENT

SECURITY AND RESILIENCY

ATTACKER INTENT

Cause systems to crash

SECURITY AND RESILIENCY

ATTACKER INTENT

Cause systems to crash

NOT CONCERNED WITH DATA BEING STOLEN

SECURITY AND RESILIENCY

ATTACKER INTENT

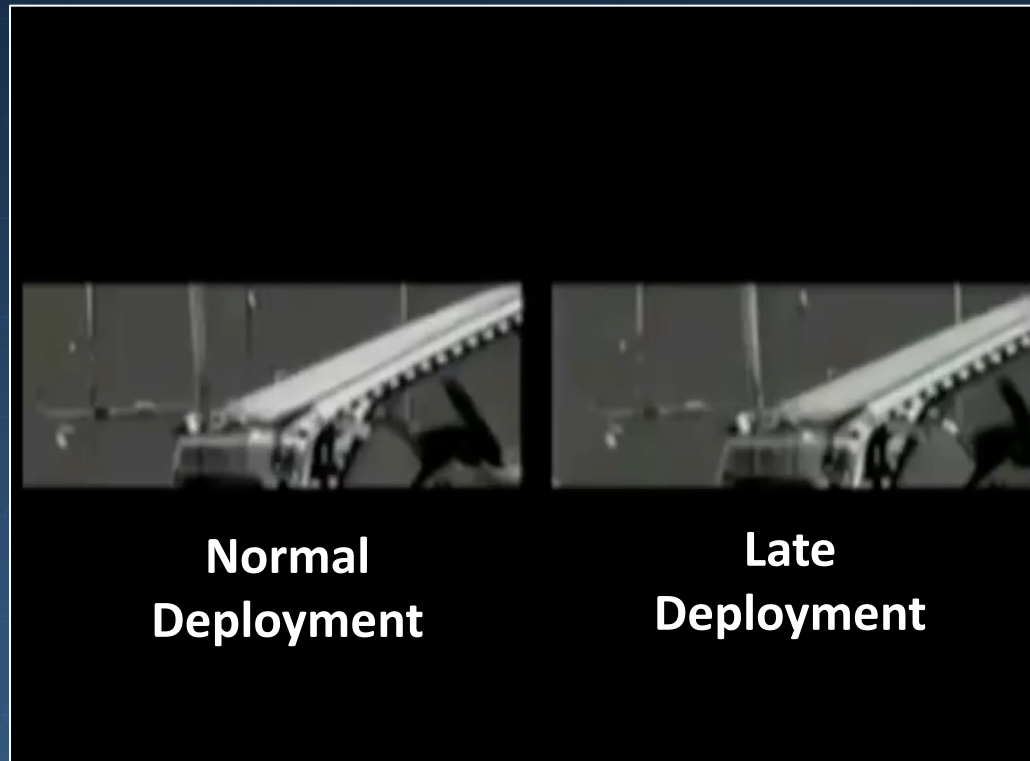
Cause systems to crash

What if airbag deployment is delayed?

SECURITY AND RESILIENCY

ATTACKER INTENT

Cause systems to crash





Next Lecture

- **Design** of Autonomous Systems
- **Sensing**
 - IMU, GPS, Radar, LIDAR, Camera, etc.