

Secure Autonomous and Cyber- Physical Systems

CS 599 001/ECE 599 004

Winter 2022

Prof. Sabin Mohan

<https://bit.ly/secureauto2022>

Definitions

Autonomy

Cyber-Physical Systems

Real-Time Systems

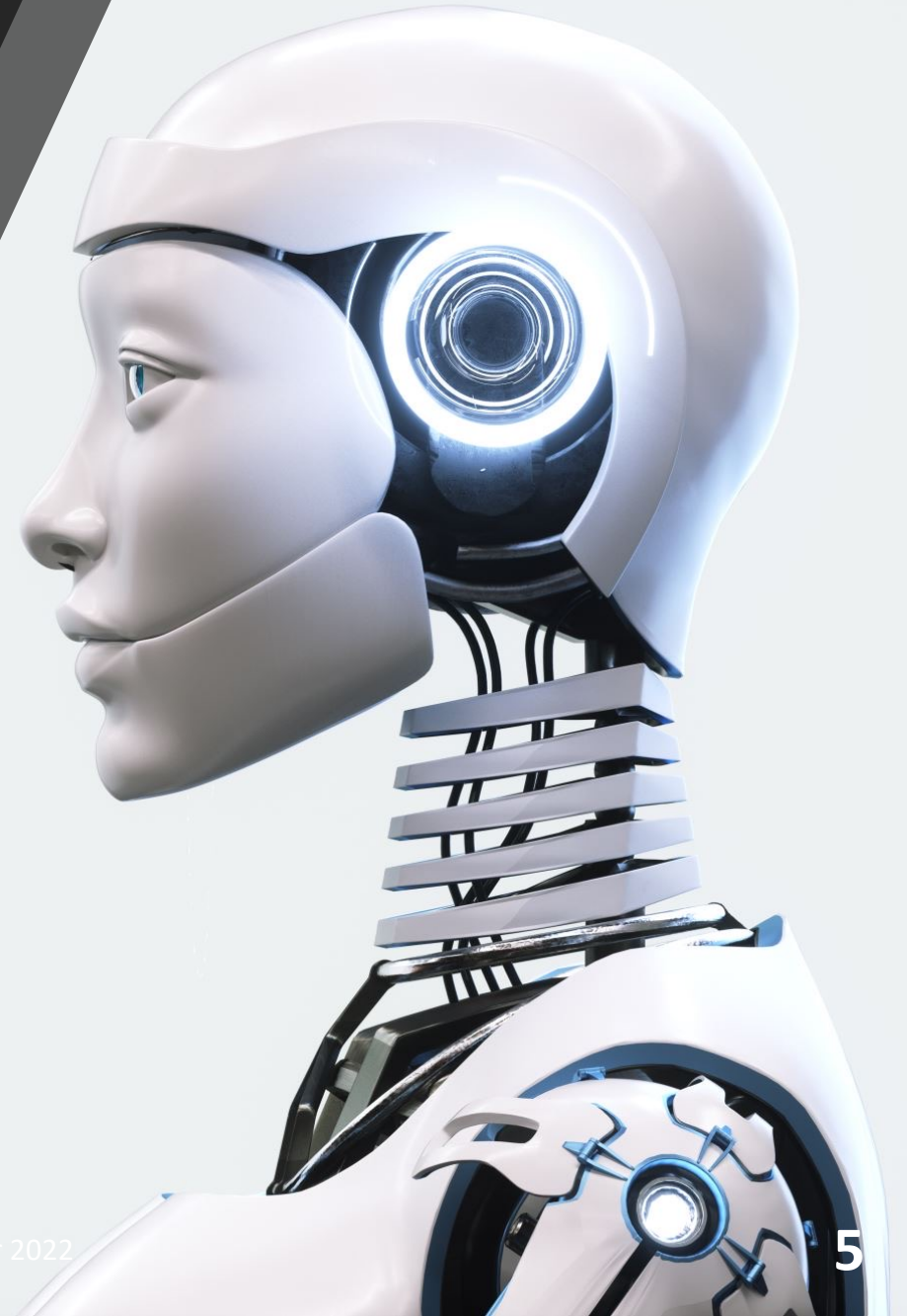
Autonomy



Aspects of Autonomy?

Autonomy | A Definition

Autonomy is the **ability to perform given tasks** based on the **system's perception** **without** human intervention



Detour | This Course

Secure Autonomous and Cyber-Physical Systems (CPS)

CS 599 001/ECE 599 004

Instructor: **Prof. Sibin Mohan** [Sibin/Prof. Sibin/Prof. Mohan]

Days/Times: **MON/WED 2 PM – 3:50 PM**

Location: **BAT 150**

Contact: **Canvas**

Office Hours: **MON/WED 4:00 – 5:00 PM [KEC 3049]**

Course Content

- *design* of autonomous, cyber-physical and real-time systems
- *sensing*, IMU, GPS, Radar, LIDAR, Camera, etc.
- *localization*, Simultaneous localization And Mapping (SLAM)
- Extended Kalman Filter (EKF)
- *attacks* and *defenses* related to all of these topics
- *privacy and ethical issues* in the design and deployment of autonomous systems

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Security

<https://bit.ly/secureauto2022>

Course Content | MPs

- Hands-on exercises [3]
- open-source simulation and control platforms
 - Gazebo
 - VEINS
- Final MP will have a leaderboard-style competition!

<https://bit.ly/secureauto2022>

Course Content | Paper Reading+Presentation

- Exploring state-of-the-art research in the area
- Learn how to **read** and **critique** relevant papers
- Present papers in class
 - Each student presents **two papers** over the course of the term

<https://bit.ly/secureauto2022>

Grading Criteria

| | |
|------------------------------------|------------|
| In-class participation | 5% |
| MP1 [V2X/VEINS] | 20% |
| MP2 [UAV Security/Gazebo] | 20% |
| MP3 [V2X Attack/Leaderboard/VEINS] | 25% |
| Paper Reading/Critique | 30% |

Grades

Conversion from numerical to letter grades

| | | |
|----------|---|----|
| 95 - 100 | = | A |
| 90 - 94 | = | A- |
| 87 - 89 | = | B+ |
| 83 - 86 | = | B |
| 80 - 82 | = | B- |
| 77 - 79 | = | C+ |
| 73 - 76 | = | C |
| 70 - 72 | = | C- |
| 67 - 69 | = | D+ |
| 63 - 66 | = | D |
| 60 - 62 | = | D- |
| < 60. | = | F |

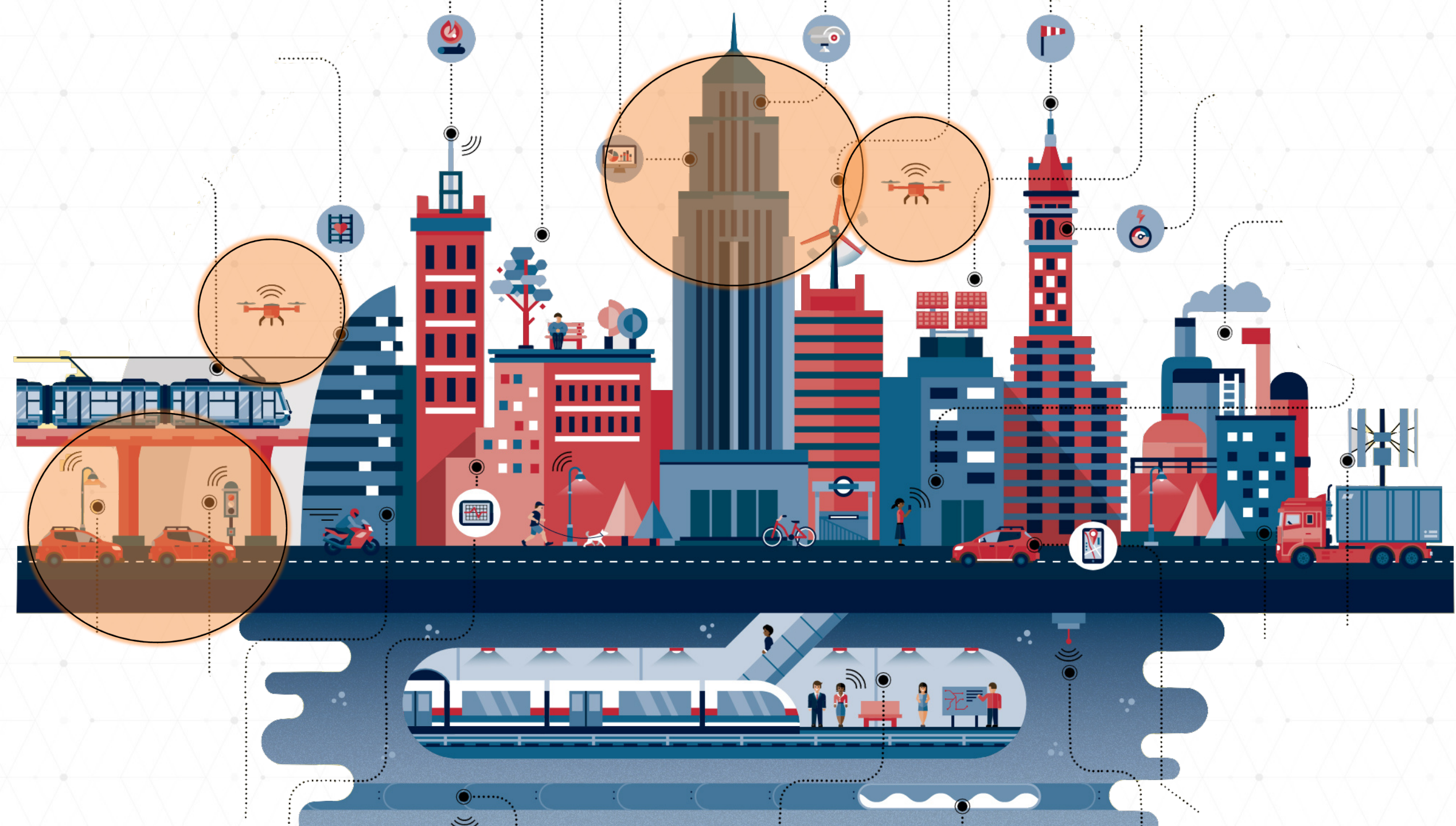
End of Detour

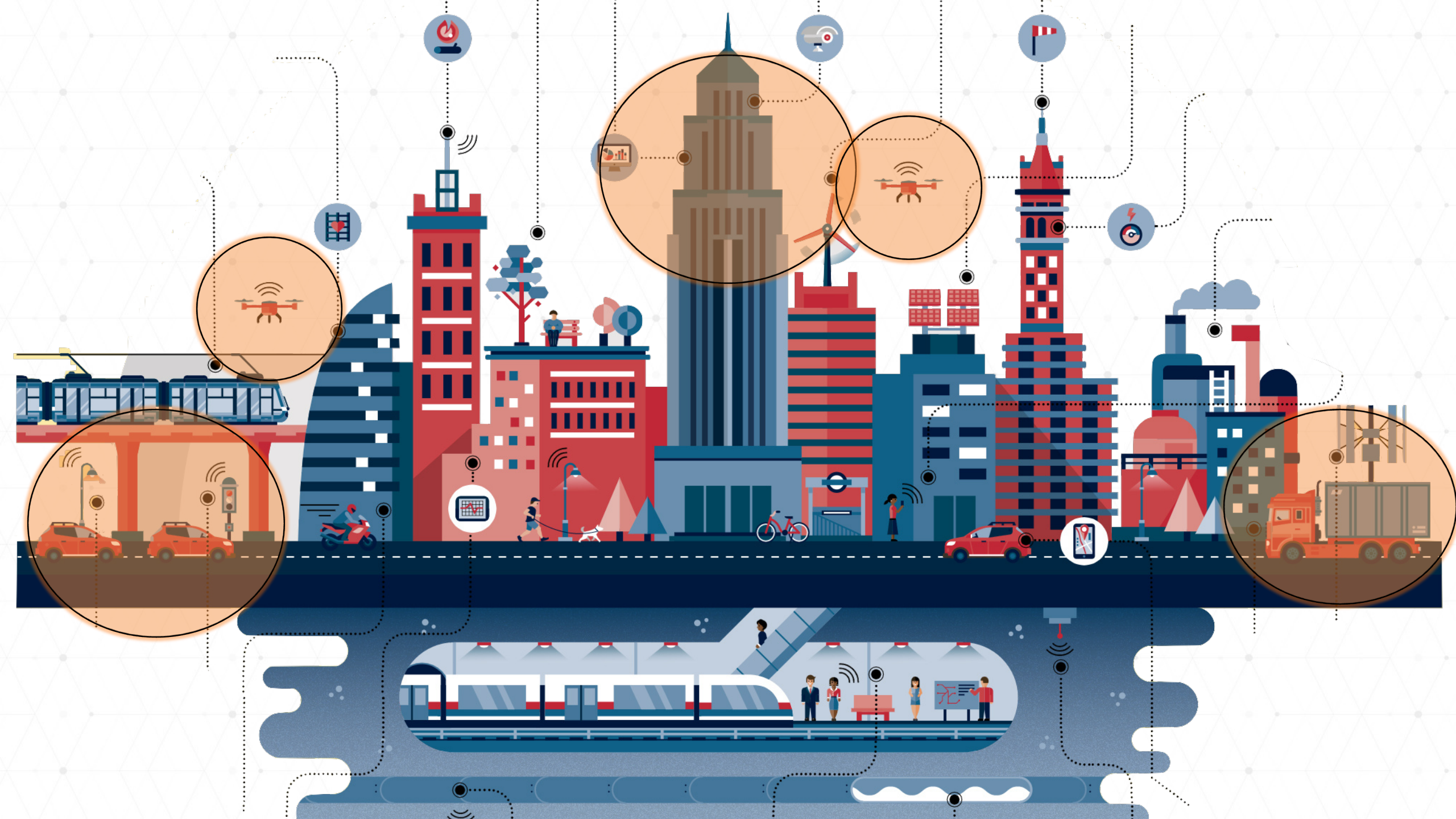
- Back to definitions/concepts
 - Cyber-Physical Systems
 - Real-Time Systems
 - Security/Safety/Resiliency







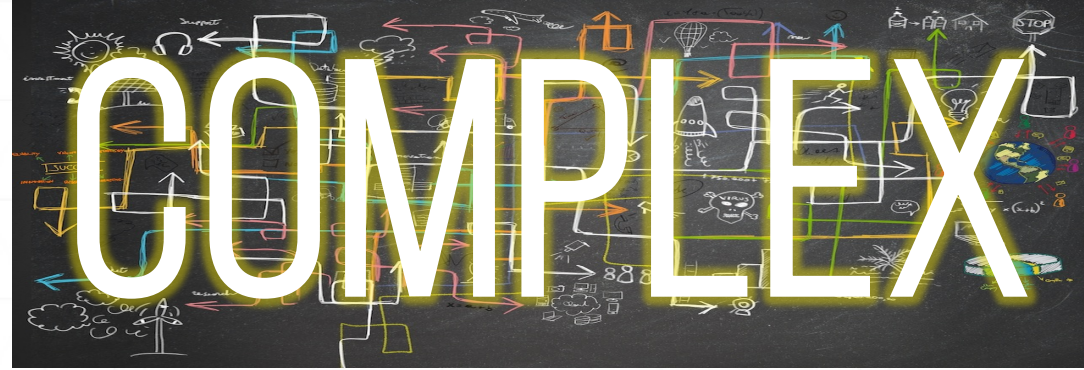




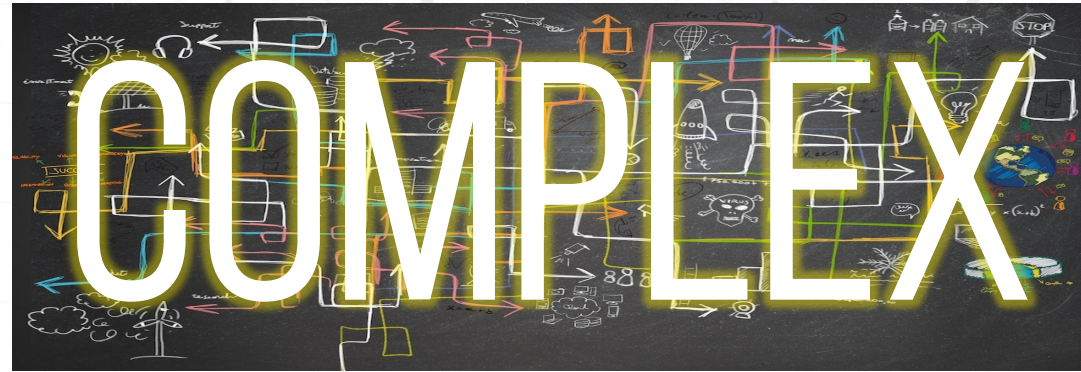


LARGE

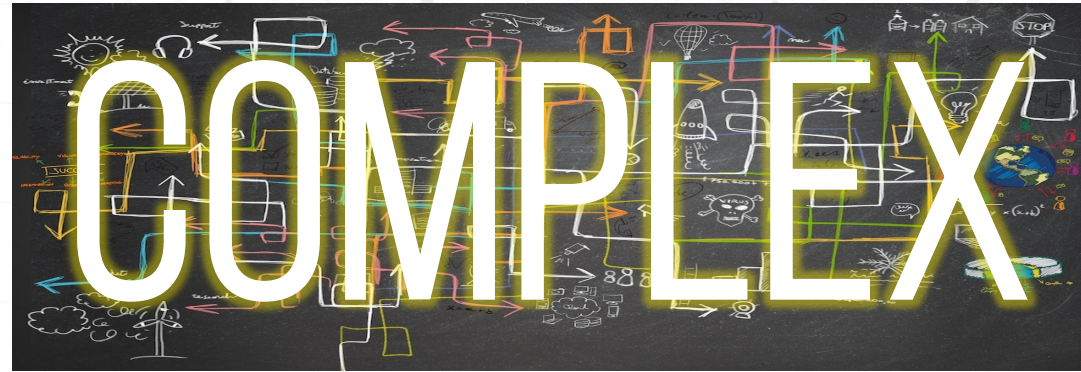
LARGE



LARGE



LARGE



SYSTEMS

LARGE

COMPLEX

MODELING, ANALYSIS, SECURITY ARE **HARD PROBLEMS**

INTERCONNECTED

SYSTEMS

CYBER-PHYSICAL SYSTEMS

CYBER-PHYSICAL SYSTEMS

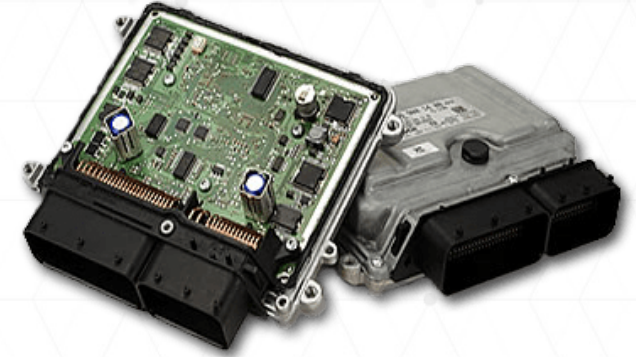
CYBER

```
05 P48A/P TS TEMPR60 # FOR GENERALIZED RETURN TO OTHER BANKS
06 TC BANKCALL # SUBROUTINE TO CHECK PGNC'S CONTROL
07 CADR G+N,AUTO# AND AUTO STABILIZATION MODES
08 CCS A # +0 INDICATES IN PGNC'S, IN AUTO
09 TCF TURNITON # + INDICATES NOT IN PGNC'S AND/OR AUTO
10 CAF APSFLBIT # ARE WE ON THE DESCENT STAGE?
11 HASK FLOWRD10
12 CCS A
13 TCF GOBACK # RETURN
14 CAF BITS # YES, CHECK FOR AUTO-THROTTLE MODE
15 EXTEND
16 RAND CHAN30
17 EXTEND
18 BZF GOBACK # IN AUTO-THROTTLE MODE -- RETURN
19 CAF P48A/PPD # DISPLAYS V50N25 R1=203 PLEASE PERFORM
20 TC BANKCALL # CHECKLIST 203 TURN ON PGNC'S ETC.
21 CADR GOPERF1
22 TCF GOTOP00H # V34E TERMINATE
23 TCF P48A/P # RECYCLE
24 GOBACK CA TEMPR60
```

software, control algorithms, code



networking, communication



ECUs, microcontrollers, PLCs

CYBER-PHYSICAL SYSTEMS

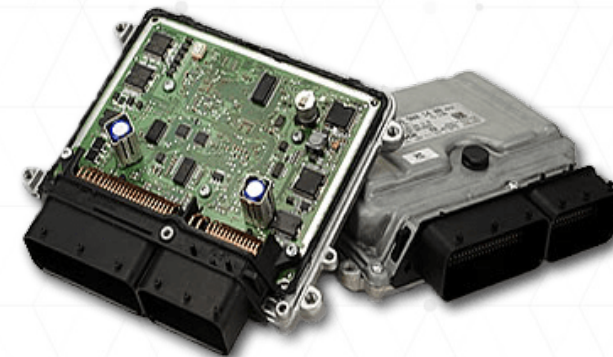
CYBER

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05 TS      TEMPR60      # FOR GENERALIZED RETURN TO OTHER BANKS
06 TC      BANKCALL    # SUBROUTINE TO CHECK PGNC'S CONTROL
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```

software, control algorithms, code



networking, communication



ECUs, microcontrollers, PLCs

PHYSICAL



sensors



actuators, motors



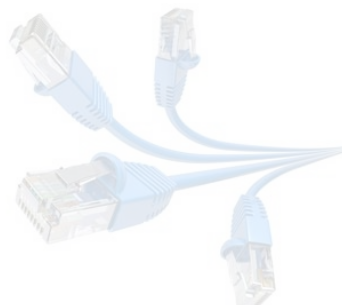
"plants"

CYBER-PHYSICAL SYSTEMS

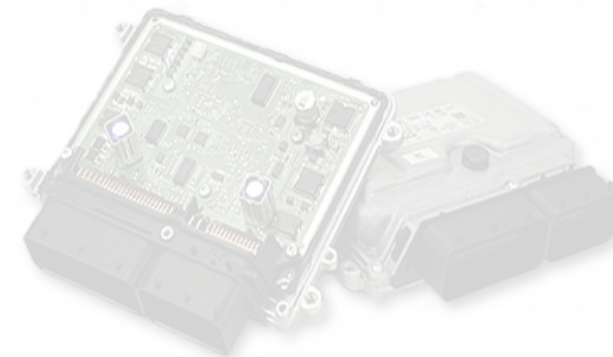
CYBER

| | | | |
|----------|--------|--|---|
| P4BA/P | TS | TEMP00 | # FOR GENERALIZED RETURN TO OTHER BANKS |
| | TC | BANKCALL | # SUBROUTINE TO CHECK PONGS CONTROL |
| | CADR | G4R,AUTOH AND AUTO STABILIZATION MODES | |
| | CCS | A | # *B INDICATES IN PONGS, IN AUTO |
| | TCF | TURNITON | # * INDICATES NOT IN PONGS AND/OR AUTO |
| | CAF | APDFLEET | # ARE WE ON THE DESCENT STAGE? |
| | MAK | FLIGHT018 | |
| | CCS | A | |
| | TCF | G0BACK | # RETURN |
| | CAF | BITS | # YES, CHECK FOR AUTO-THROTTLE MODE |
| | EXTEND | | |
| | RAND | CHAN30 | |
| | EXTEND | | |
| | RZF | G0BACK | # IN AUTO-THROTTLE MODE -- RETURN |
| TURNITON | CAF | P4BA/PTD | # DISPLAYS V50N25 R1+203 PLEASE PERFORM |
| | TC | BANKCALL | # CHECKLIST 203 TURN ON PONGS ETC. |
| | CADR | G0PERF1 | |
| | TCF | G0TOP00H | # V34E TERMINATE |
| | TCF | P4BA/P | # RECYCLE |
| G0BACK | CA | TEMP00 | |

software, control algorithms, code



networking, communication



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sensors



actuators, motors

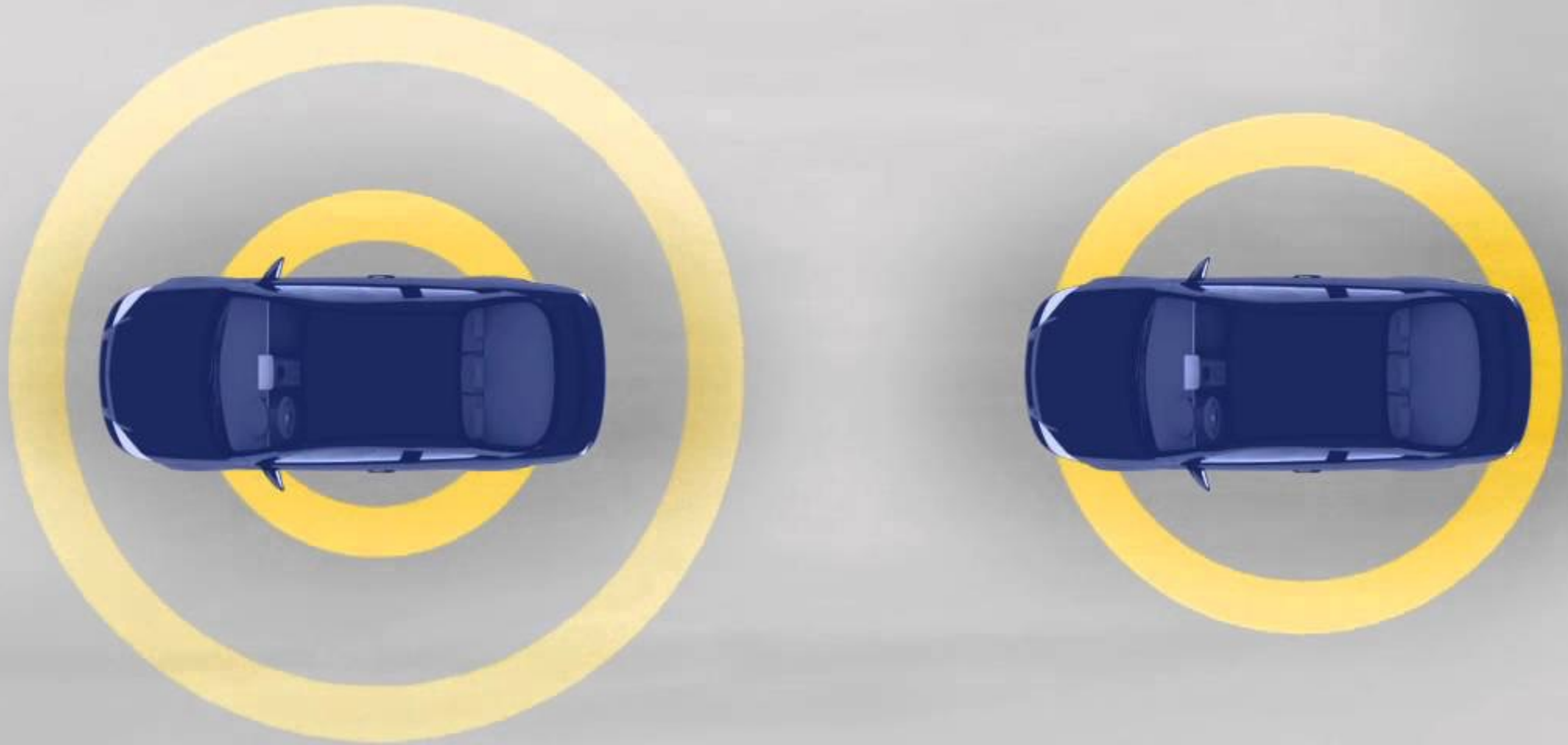


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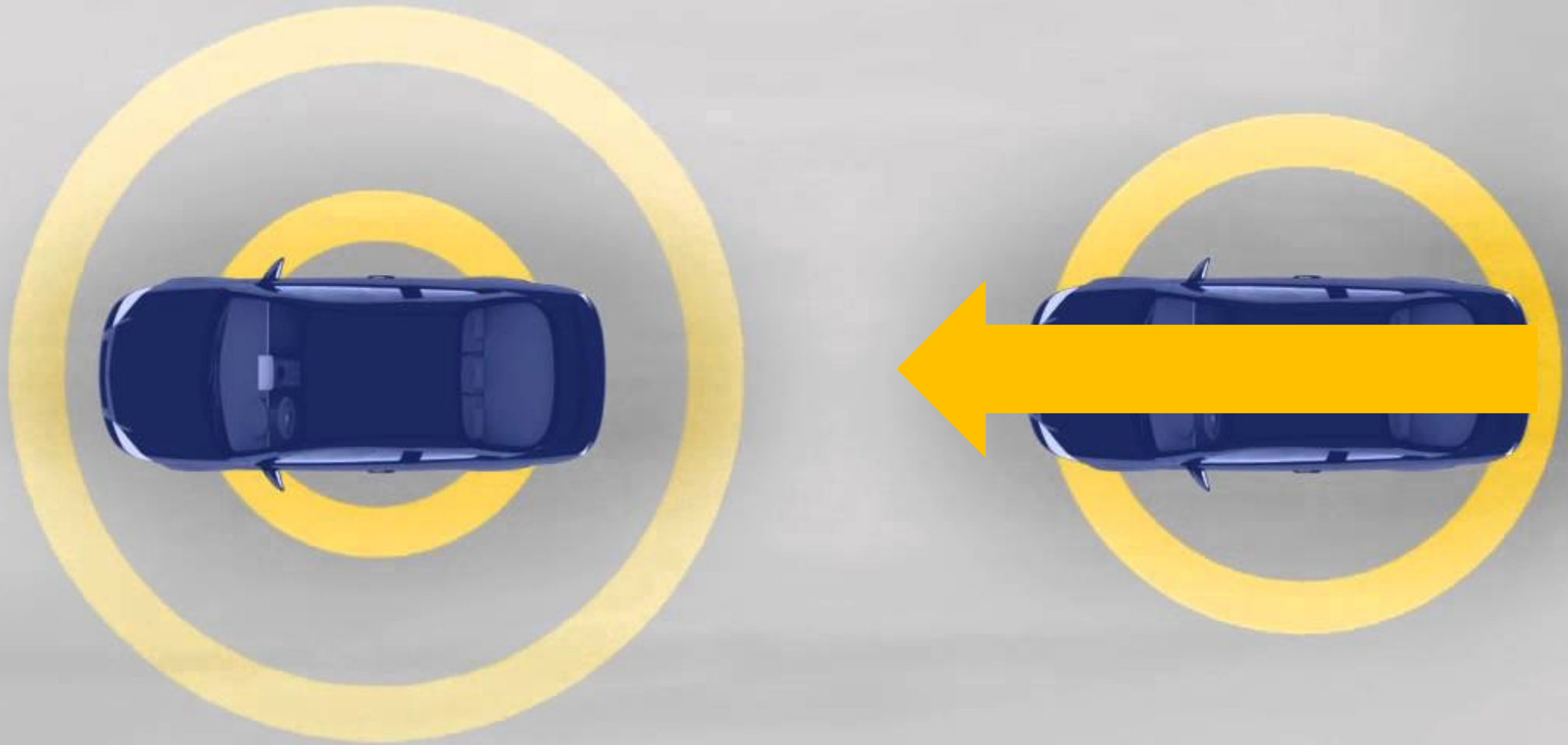


SENSING AND ACTUATION IS EVERYWHERE

SENSING/ACTUATION IN THE REAL WORLD

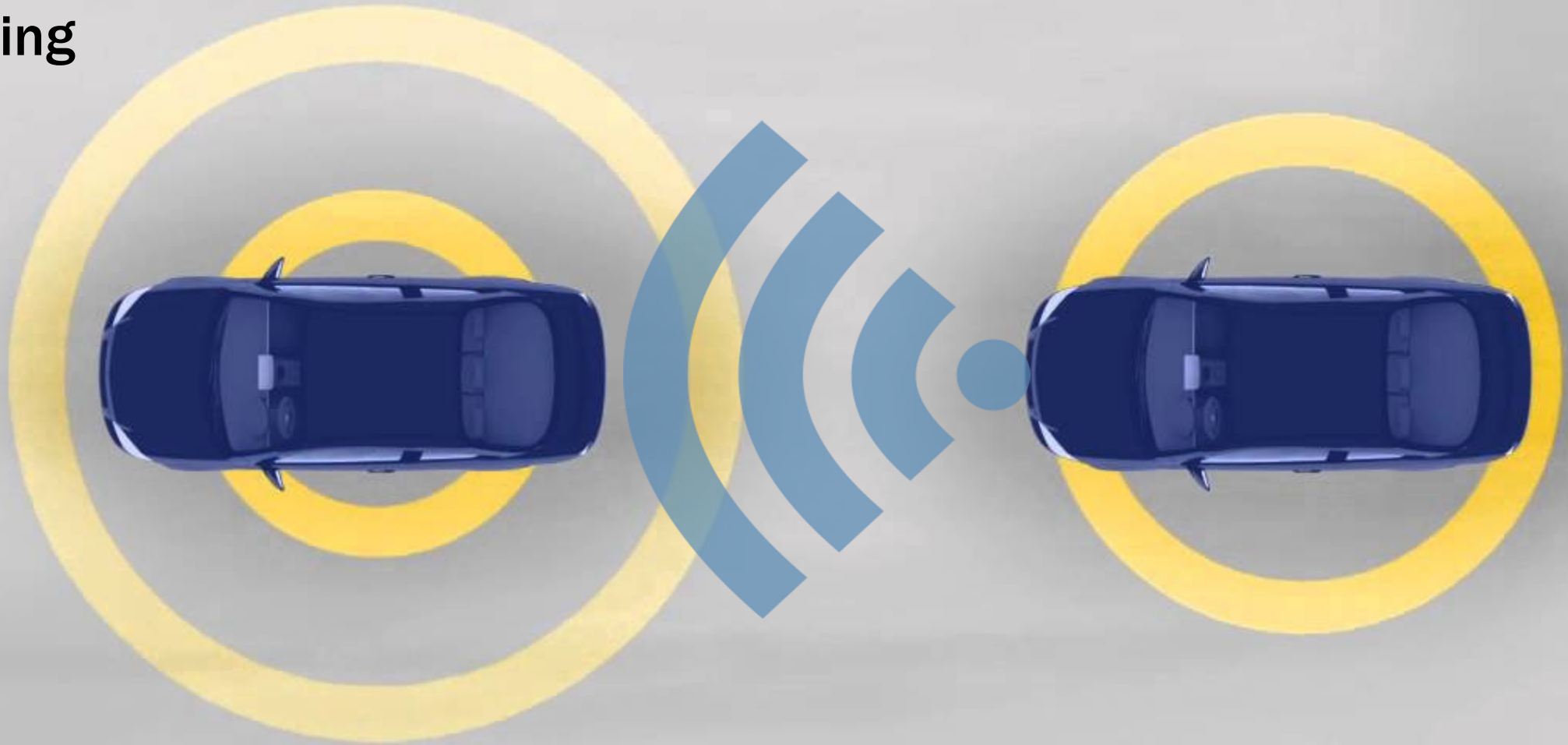


SENSING/ACTUATION IN THE REAL WORLD



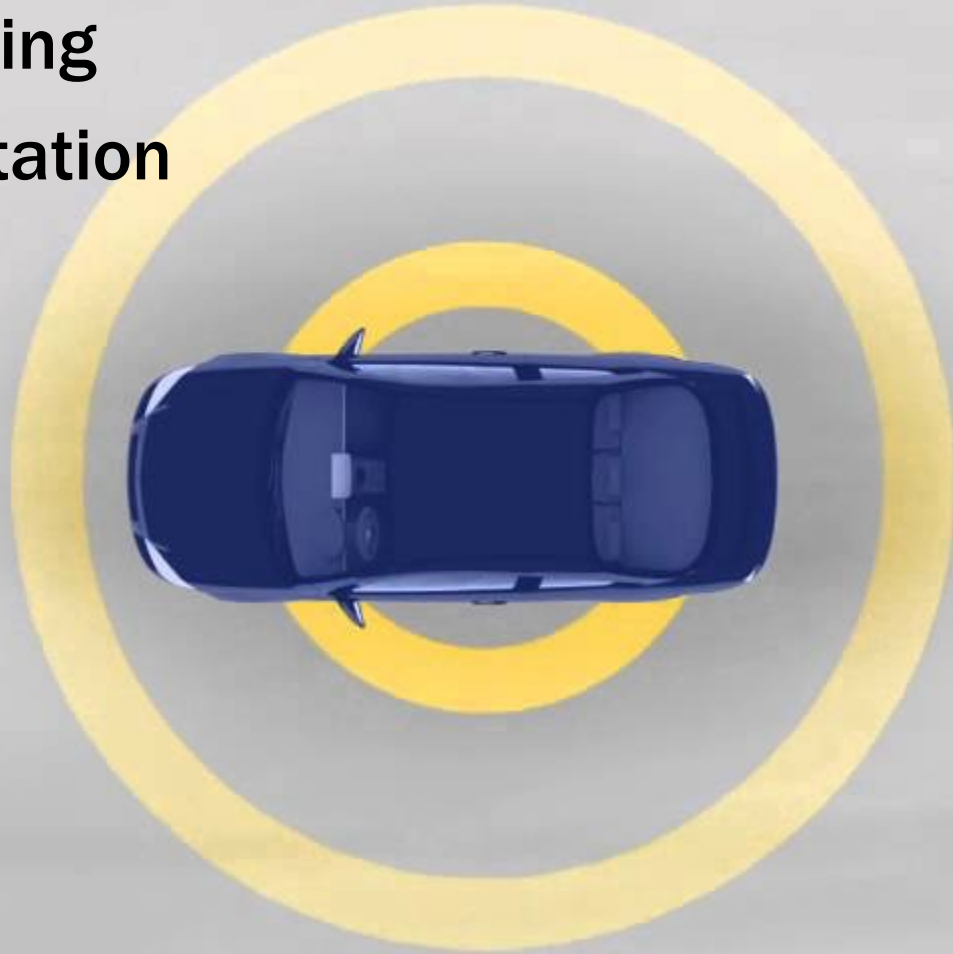
SENSING/ACTUATION IN THE REAL WORLD

- Periodic Sensing



SENSING/ACTUATION IN THE REAL WORLD

- Periodic Sensing
- Quick computation



SENSING/ACTUATION IN THE REAL WORLD

- Periodic sensing
- Quick computation
- In time actuation



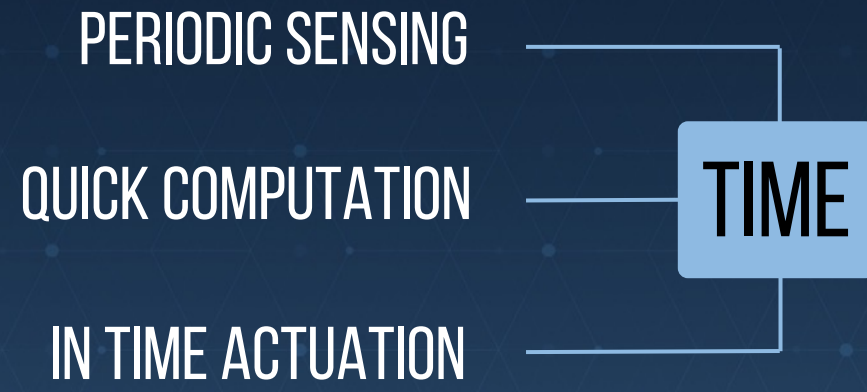
BRAKING



PERIODIC SENSING

QUICK COMPUTATION

IN TIME ACTUATION



REAL-TIME SYSTEMS

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“A system that requires both, **logical** as well as **temporal** correctness.”

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- **Temporal correctness defined as a constraint: deadline**

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- **Deadlines determine usefulness of results**
 - **Deadline passes → usefulness drops**

REAL-TIME SYSTEMS

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- **Use well-defined scheduling algorithms [e.g. RM, EDF]**

REAL-TIME SYSTEMS

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- **Deadlines determine usefulness of results**
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ONE OF THE FOUNDATIONAL AREAS FOR CYBER-PHYSICAL SYSTEMS

REAL-TIME SYSTEMS

Consider an airbag deployment system



REAL-TIME SYSTEMS

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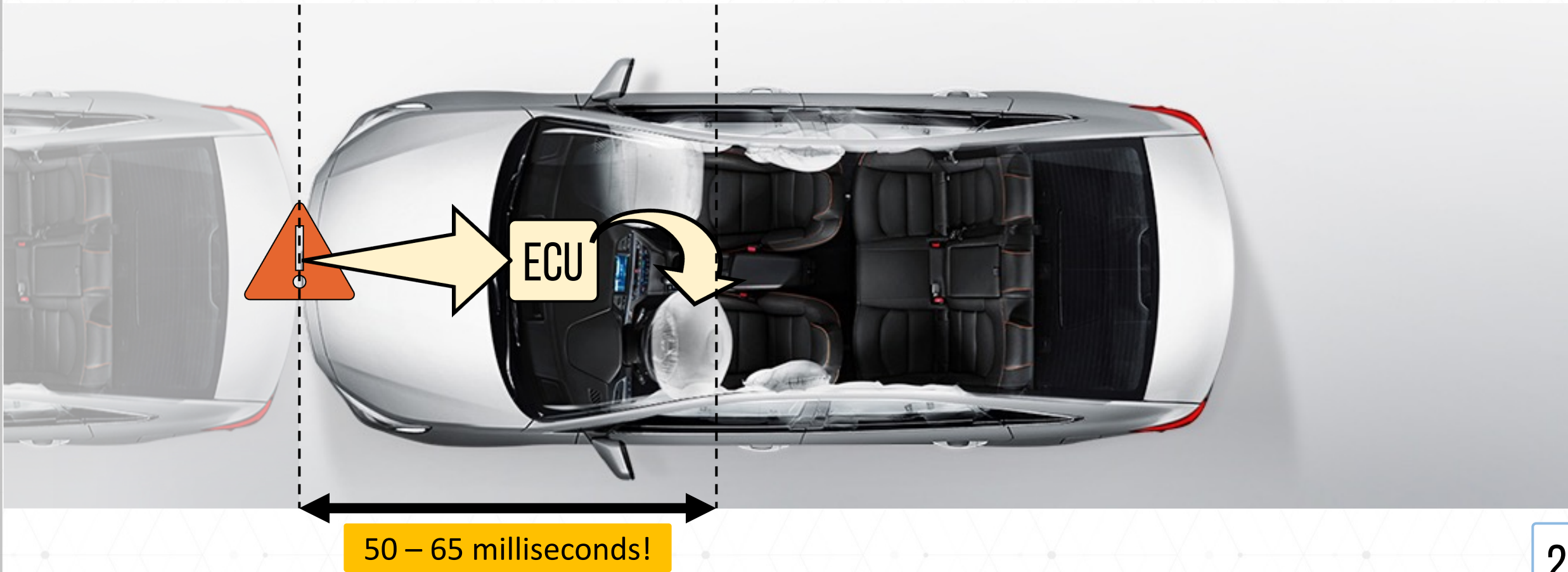
REAL-TIME SYSTEMS

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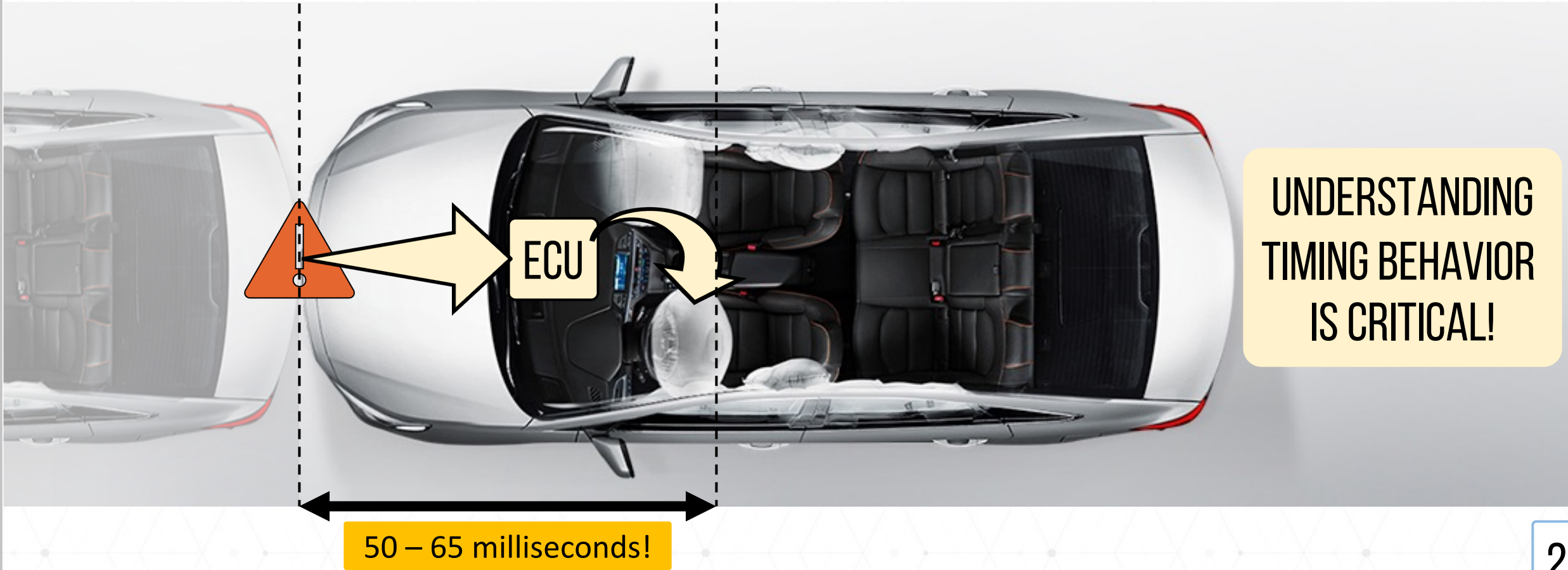
REAL-TIME SYSTEMS

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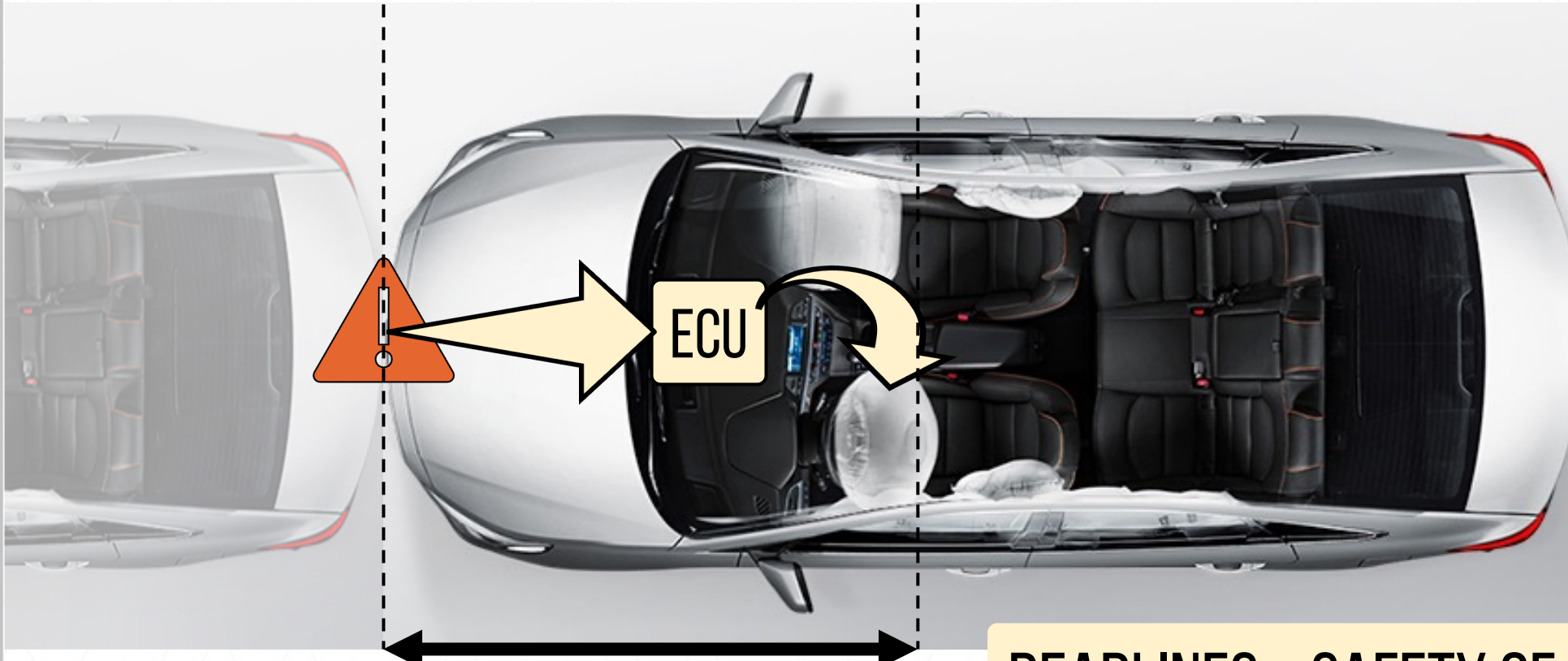
REAL-TIME SYSTEMS

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REAL-TIME SYSTEMS

Consider an airbag deployment system



UNDERSTANDING
TIMING BEHAVIOR
IS CRITICAL!

DEADLINES = SAFETY OF PHYSICAL SYSTEM

REAL-TIME SYSTEMS

Consider an airbag deployment system

WHY NOT RUN CODE REALLY FAST?

UNDERSTANDING
TIMING BEHAVIOR
IS CRITICAL!

50 – 65 milliseconds!

CPS Challenges



Limited Resources

- Computational power, energy, cost



Timing Requirement

- Safety, reliability, deadlines

CPS Challenges



Limited Resources

- Computational power, energy, cost



Timing Requirement

- Safety, reliability, deadlines



Security/System Upgradability

- Schedulability, Verifiability

CPS

SECURITY

Physically isolated

Specialized protocols & hardware

Not connected to the internet

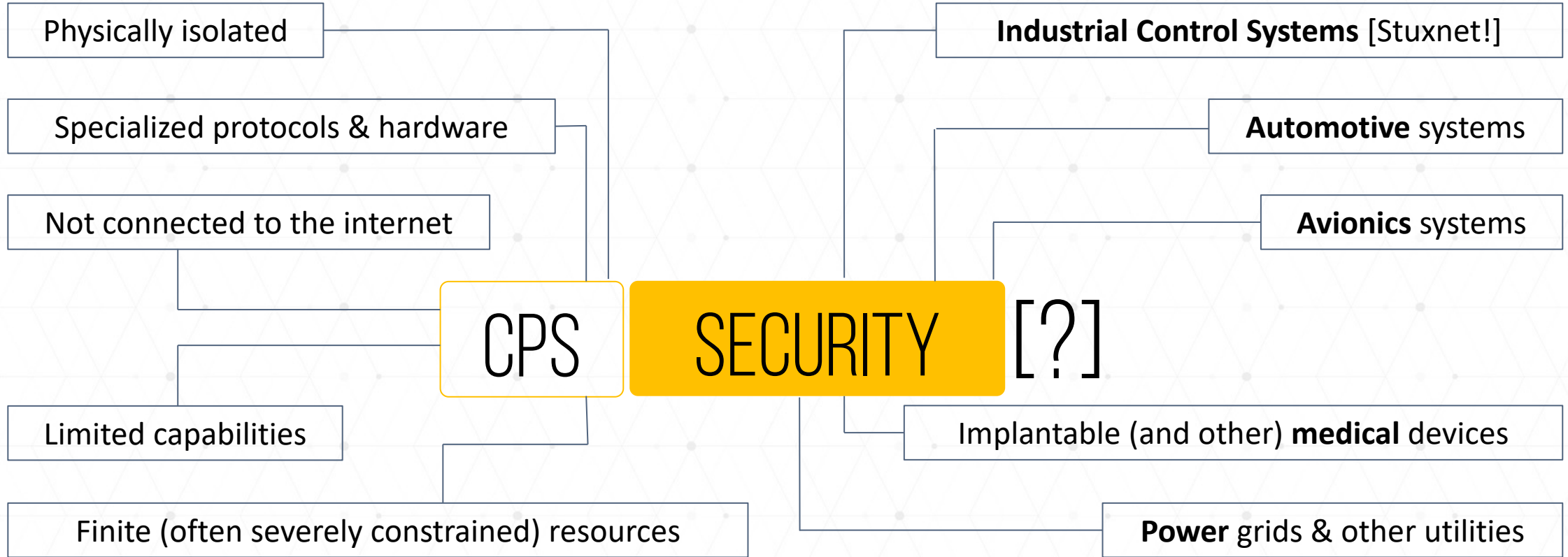
CPS

SECURITY

[?]

Limited capabilities

Finite (often severely constrained) resources



Autonomous Cars

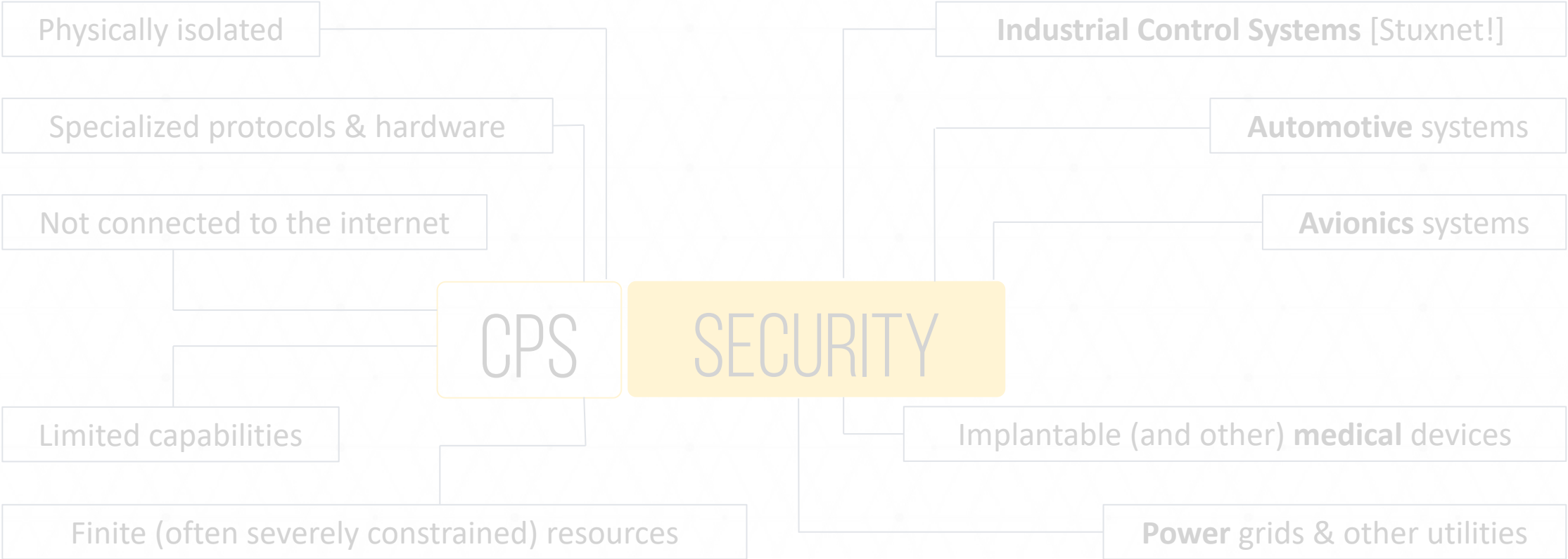
UAVs

Medical/surgical robots

IoT

Delivery robots

Smart Manufacturing Systems



Autonomous Cars

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Smart Manufacturing Systems

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CPS

SECURITY

RESILIENCY

Industrial Control Systems [Stuxnet!]

Automotive systems

Avionics systems

Implantable (and other) medical devices

Power grids & other utilities

RESILIENCY?

RESILIENCY?

SOFTWARE ERRORS CAN RESULT IN PHYSICAL FAILURES

RESILIENCY?

SOFTWARE ERRORS CAN RESULT IN PHYSICAL FAILURES



SECURITY AND RESILIENCY

SECURITY AND RESILIENCY

ATTACKER INTENT

SECURITY AND RESILIENCY

ATTACKER INTENT

Cause systems to crash

SECURITY AND RESILIENCY

ATTACKER INTENT

Cause systems to crash

NOT CONCERNED WITH DATA BEING STOLEN

SECURITY AND RESILIENCY

ATTACKER INTENT

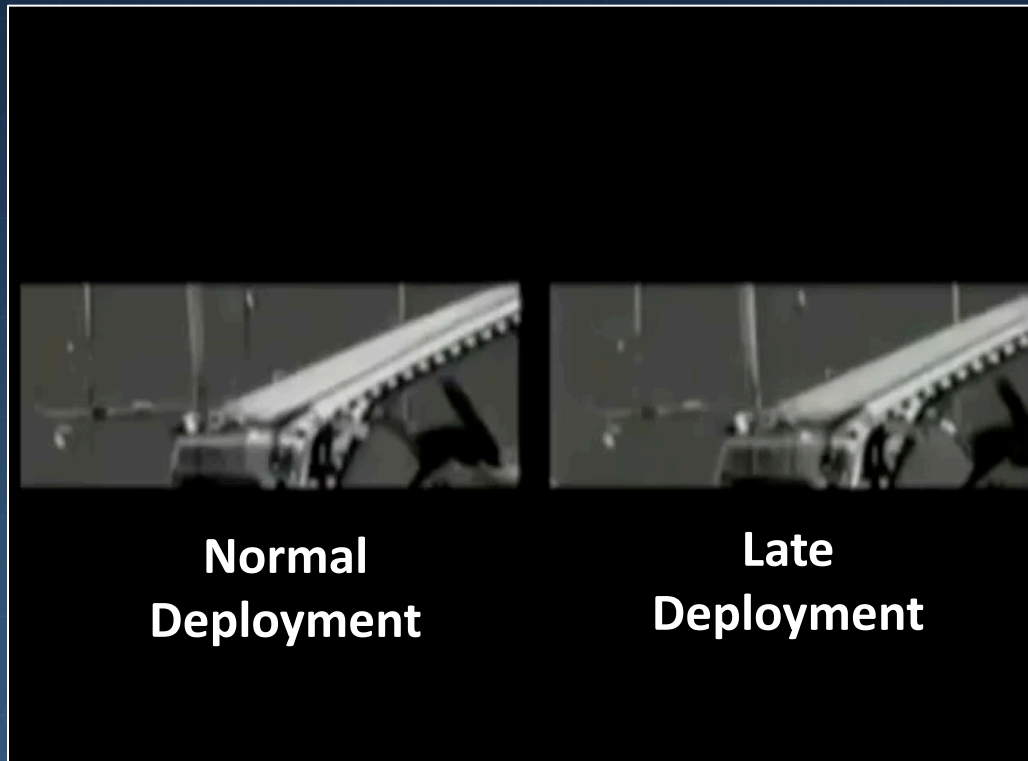
Cause systems to crash

What if airbag deployment is delayed?

SECURITY AND RESILIENCY

ATTACKER INTENT

Cause systems to crash





Next Lecture

- **Design** of Autonomous Systems
- **Sensing**
 - IMU, GPS, Radar, LIDAR, Camera, etc.